

Lattice Boltzmann multi-phase simulations using GPUs

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Ingrain

September, 22, 2010

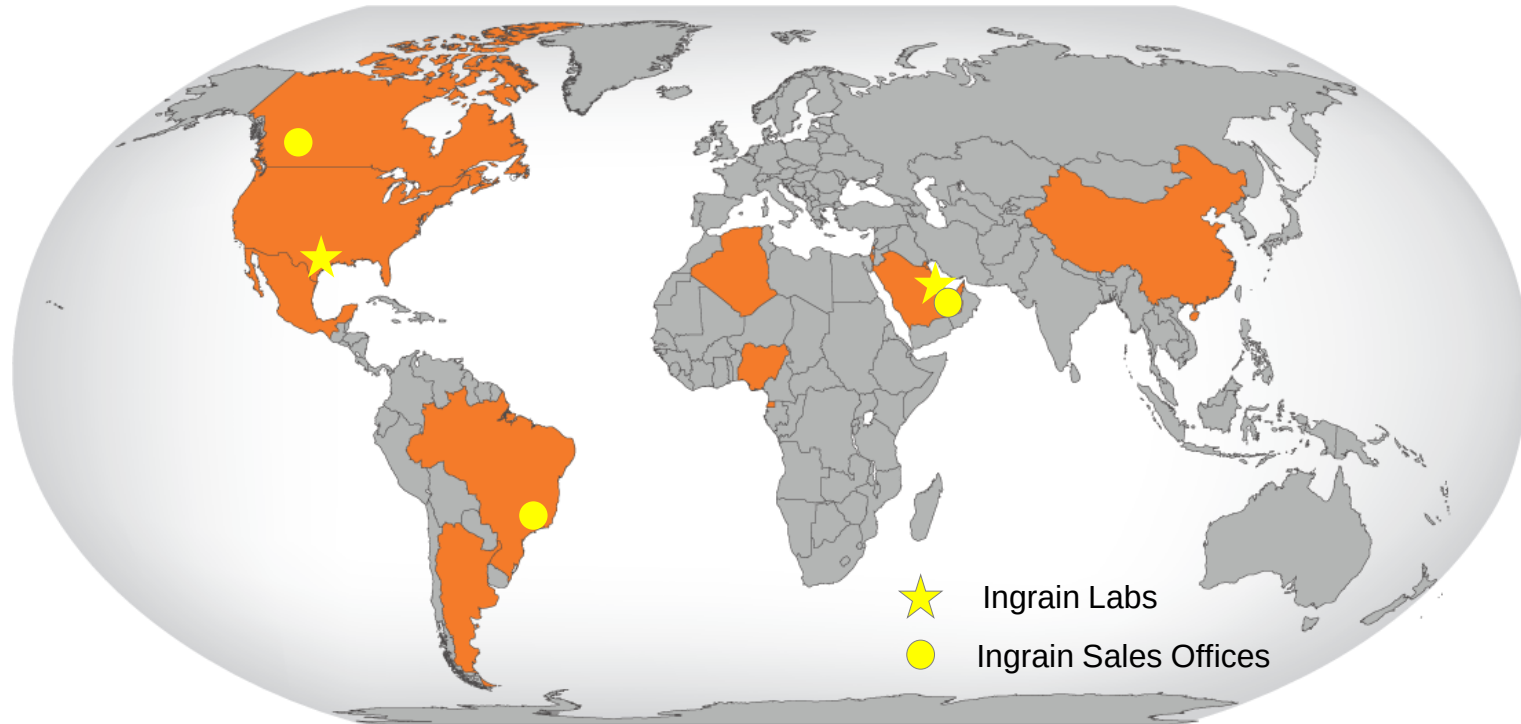
GTC 2010

San Jose, CA

- Ingrain and Digital Rock Physics
- Multiphase flow in porous media: different scales
- Lattice Boltzmann methods (LBM) on the pore scale
- GPU Programming for LBM
- Examples
- Summary and Conclusions

- Primary oil recovery (15%): oil and gas are drawn out automatically by the underground natural mechanical energy.
- Secondary oil recovery (15–20%): water is pumped in the underground to maintain the energy level.
- Tertiary oil recovery (EOR) (10-30%):
 - Gas injection
 - Chemical injection
 - Ultrasonic stimulation
 - Microbial injection
 - Thermal recovery

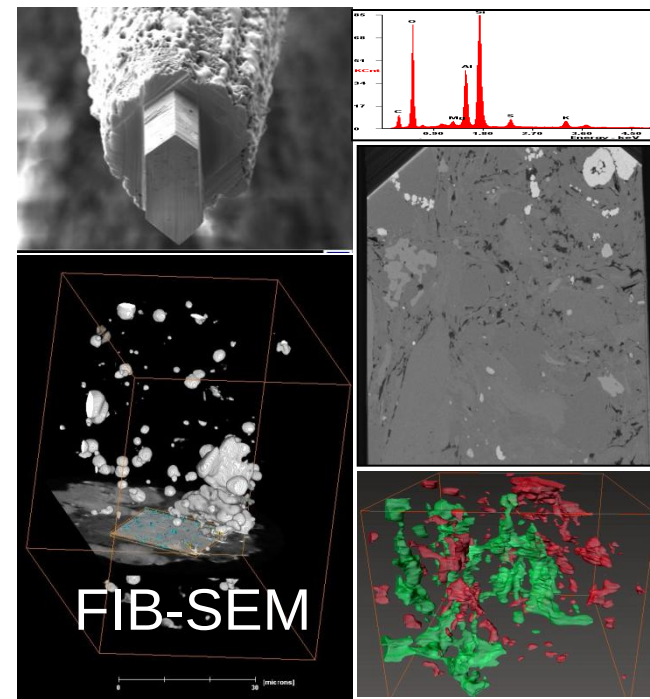
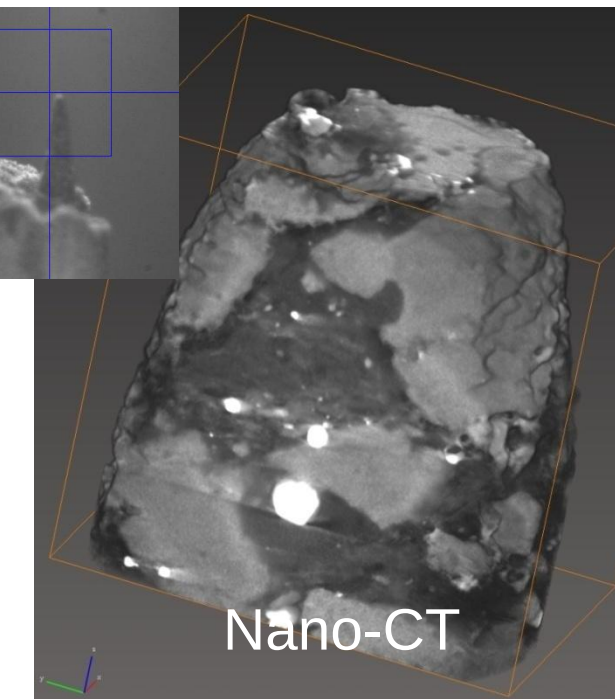
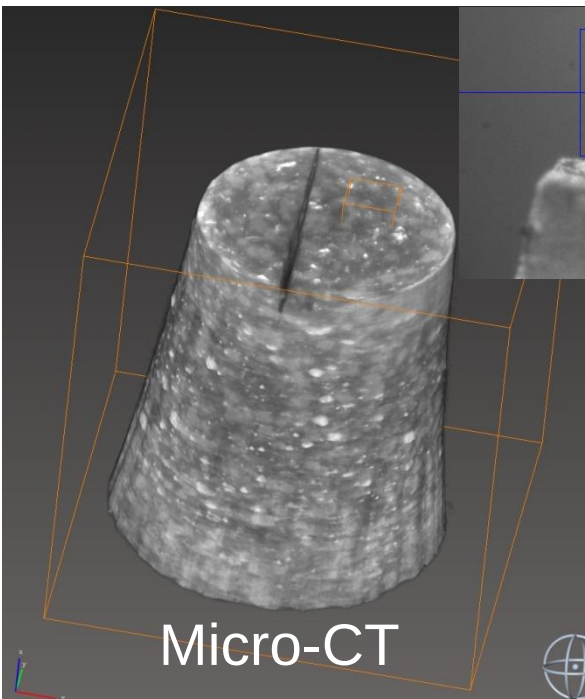
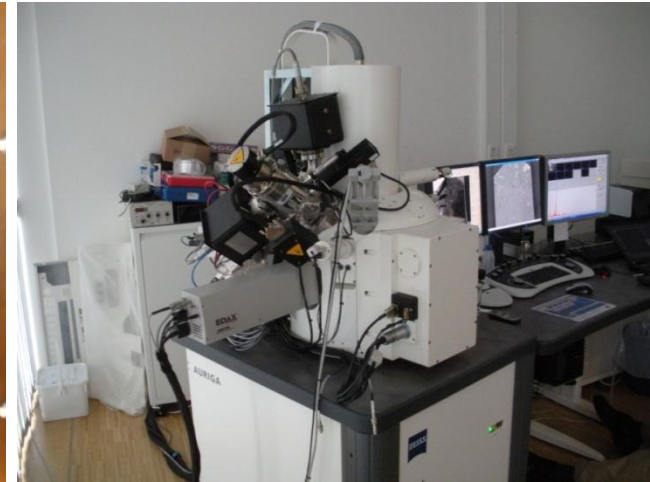
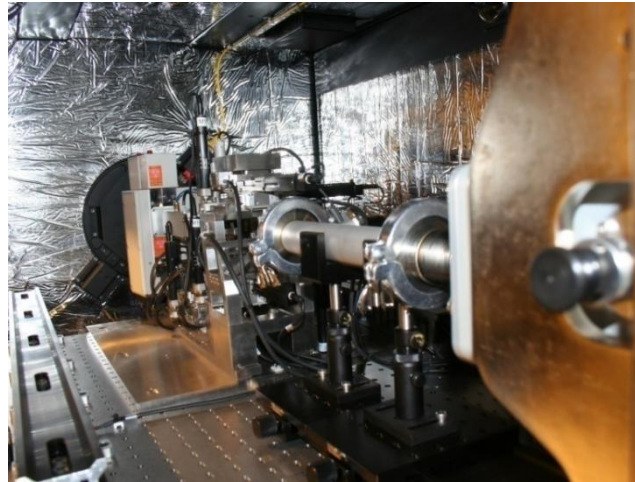
Leading oil and gas companies worldwide use
Ingrain's digital rock physics labs



- 25 US and international independents
- National oil companies in 6 countries
- 4 of 5 supermajors

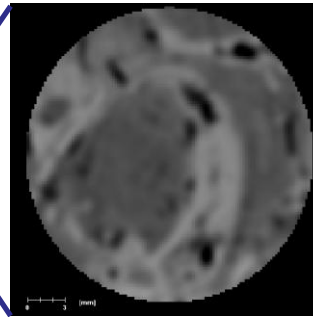
Over 4000 rock samples processed and
125 commercial jobs completed
in the past 18 months

Descending Scale systems



Ingrain images reservoir rock samples at the resolution needed to compute basic and advanced rock properties

Macro 625
625 microns/voxel



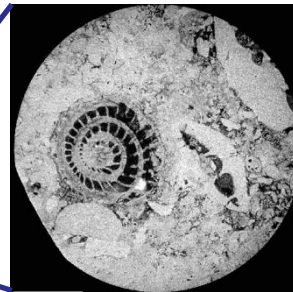
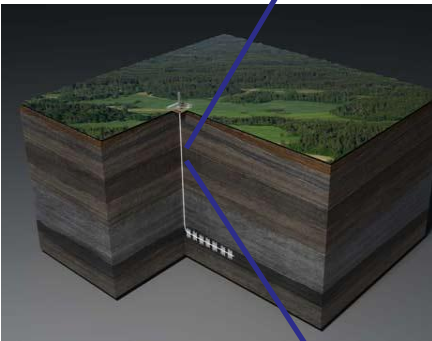
Macro 40
40 microns/voxel



Core plug (5cm)

When sampling and imaging, Ingrain uses the largest volume and lowest resolution (and therefore largest field of view) that will permit accurate computation of rock properties and fluid flow.

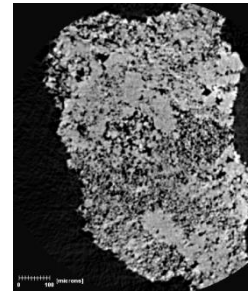
reservoir



Micro 1/2/4
1-4 microns/voxel



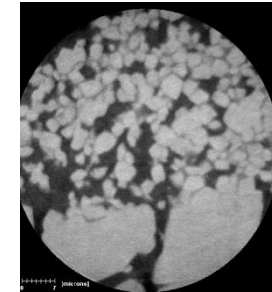
Subsample
size 1-4mm



Nano 500
500 nanometers/
voxel



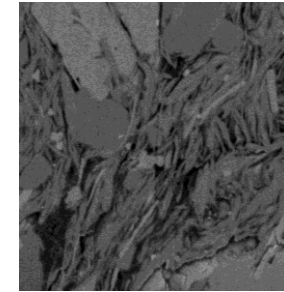
Subsample
size .5mm



Nano 65
65 nanometers/
voxel



Subsample
size .1mm



Nano 3
3 nanometers/
voxel

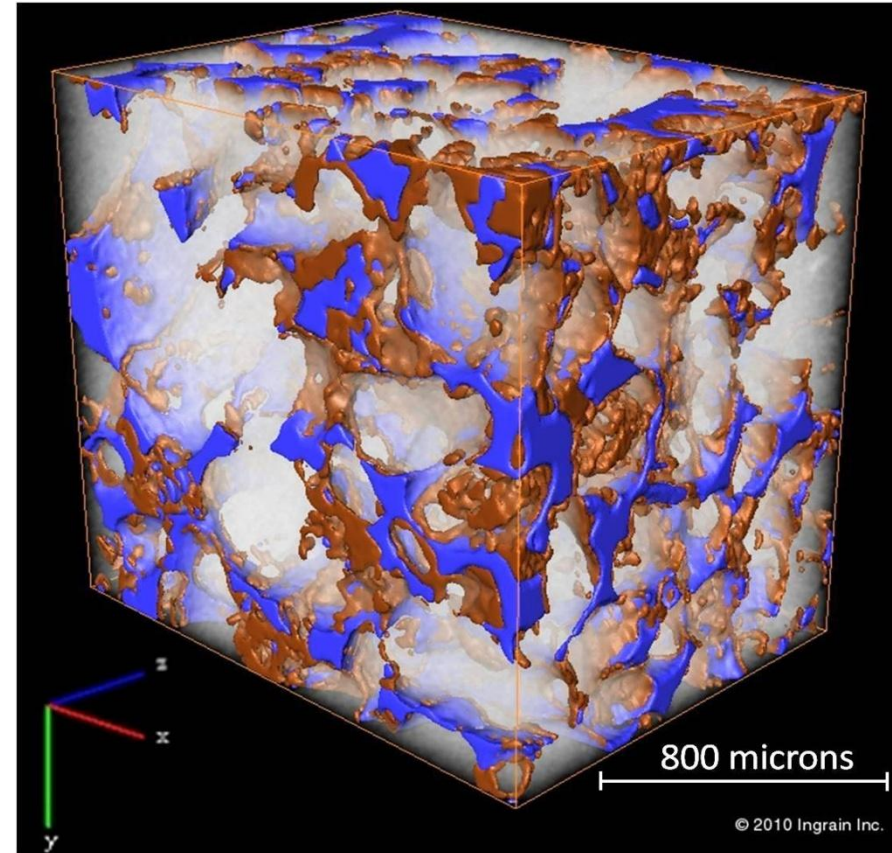


Subsample
size .1mm

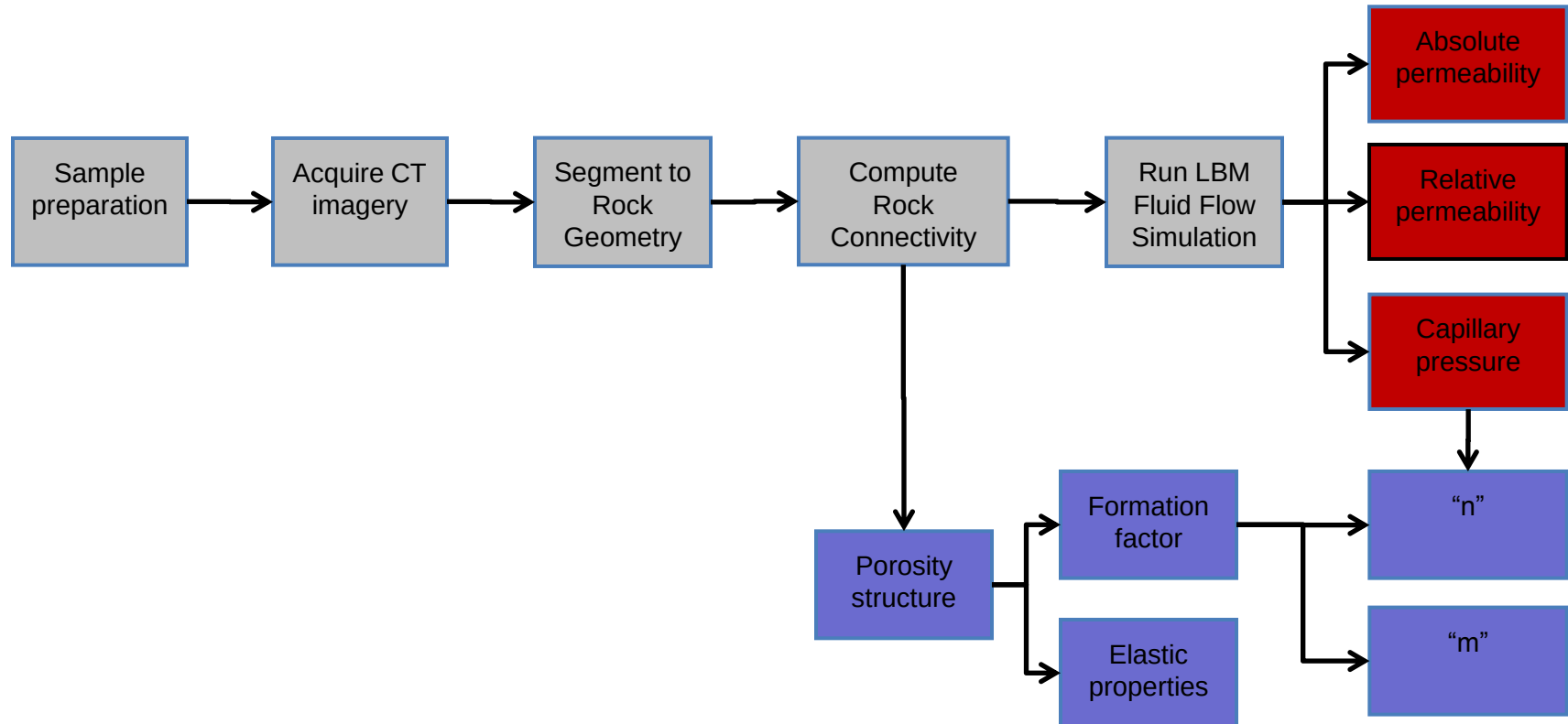
Whole core (1m)

vRock®

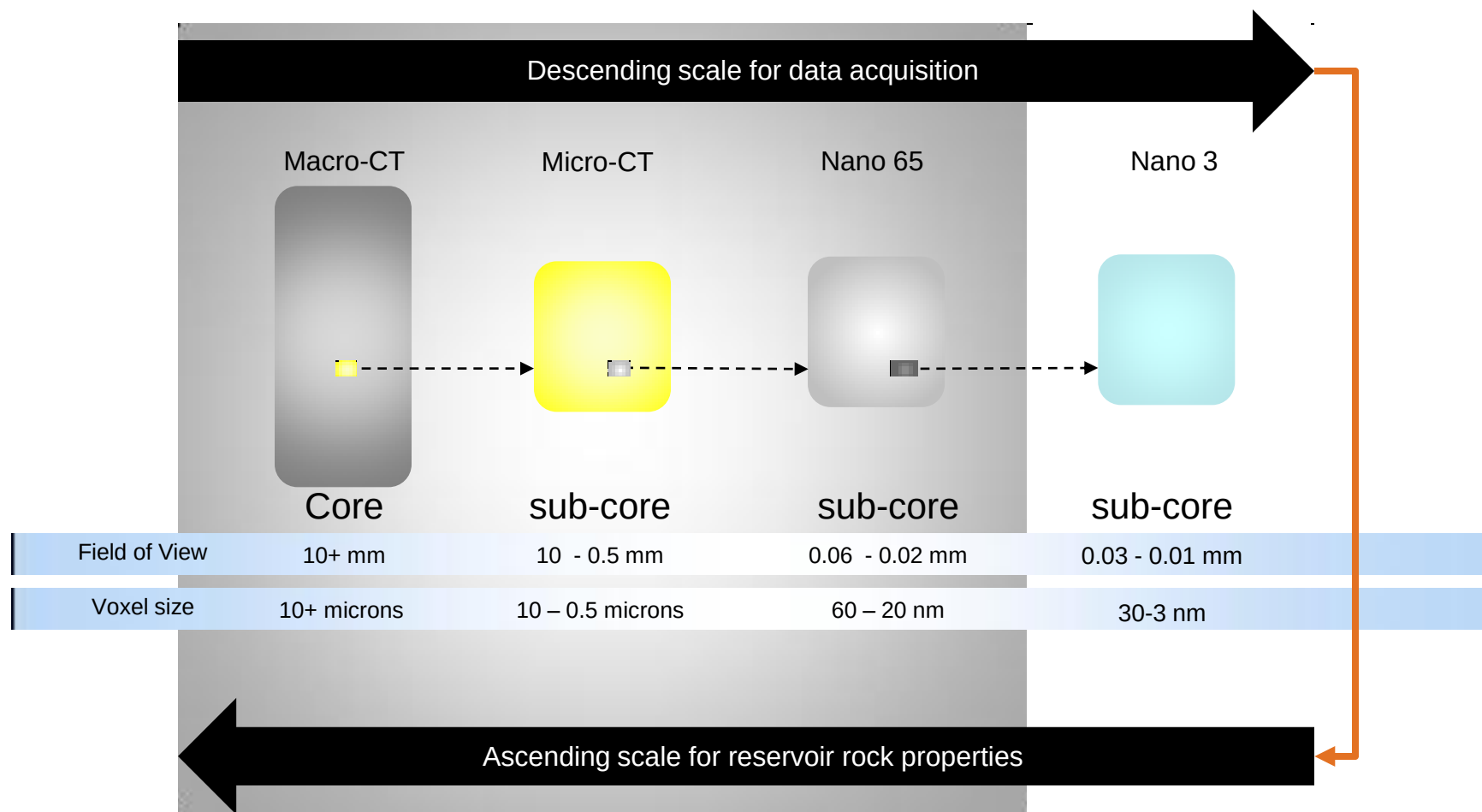
- Physical properties quickly and accurately computed from vRock® digital reservoir rocks:
 - Porosity
 - Absolute permeability in X, Y and Z directions
- Advanced rock properties computations include:
 - Formation factor in X, Y and Z directions
 - Elastic properties
 - Grain statistics
 - Two-phase relative permeability
 - Capillary pressure
- Digital subsampling capability: trend of values that reflect the heterogeneity within each rock sample
- Ingrain permanently stores each vRock® in a secure digital rock physics database



Work Flow to obtain rock properties on the pore scale



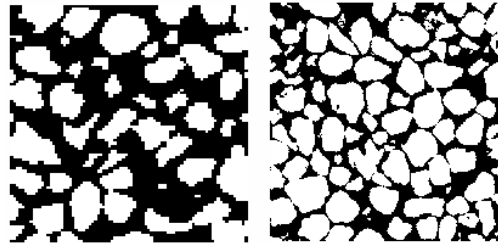
Imaging and Upscaling from Pore to Core



Flow in porous media– different scales

Pore-scale:

- Multiphase (Navier-)Stokes



↓ upscaling ↓

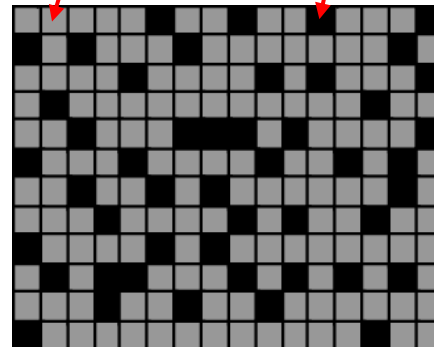
Darcy-Scale:

- Multiphase Darcy



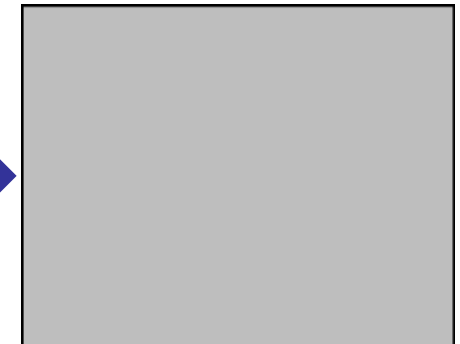
upscaling

Heterogenous Darcy-Scale



upscaling

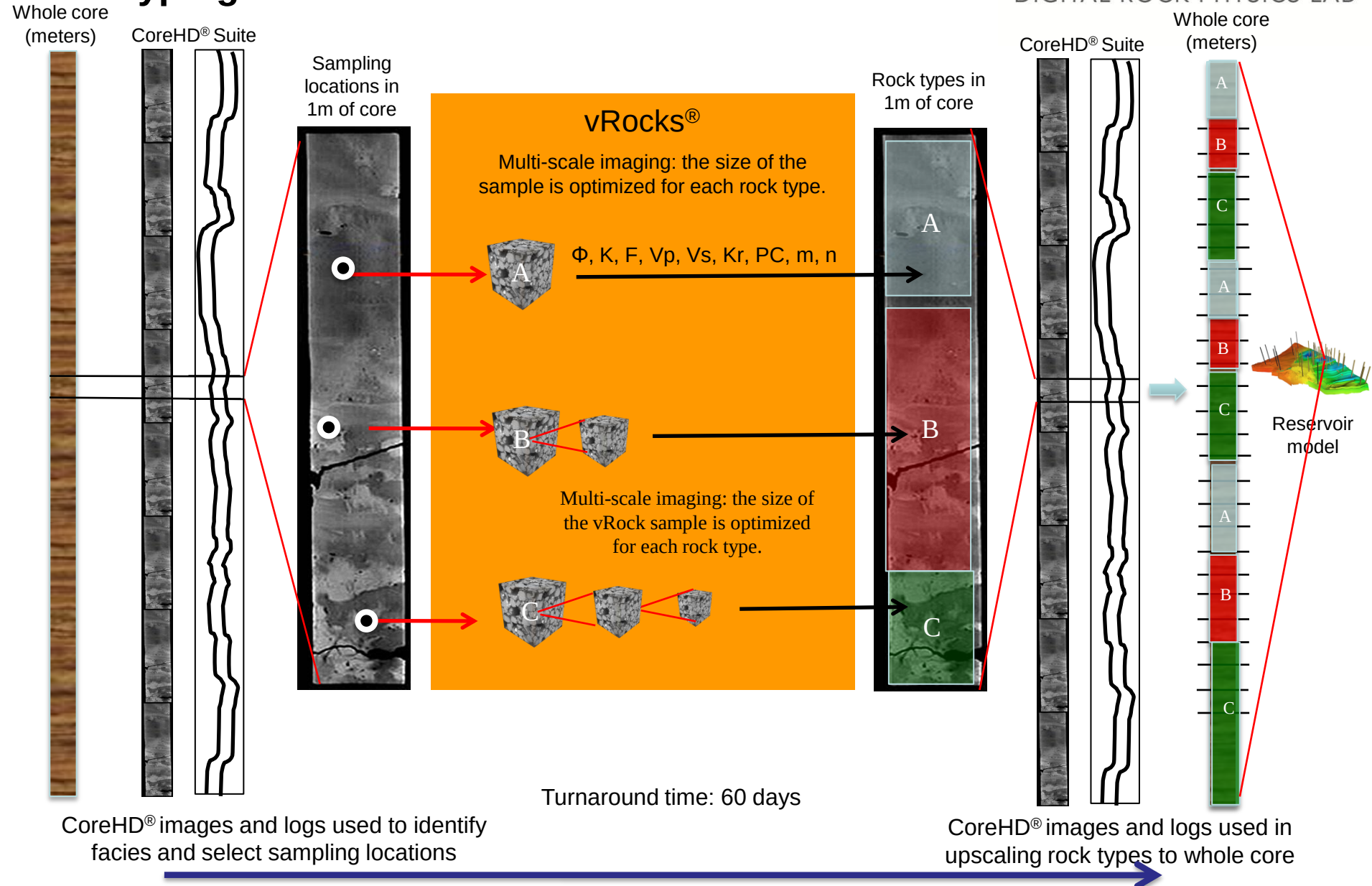
Homogenous Darcy-Scale



Ingrain's multi-scale "pore to core" approach to rock typing

INGRAIN

DIGITAL ROCK PHYSICS LAB

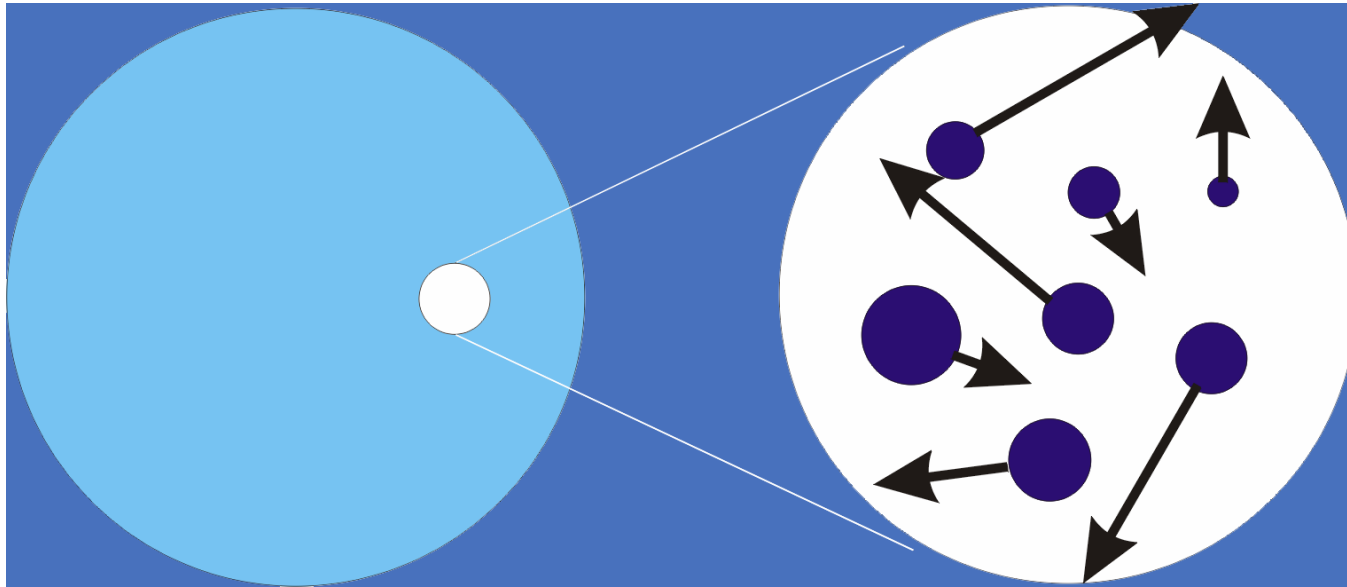


Fluid (Continuum)

$$p, \nu, \vec{u}(\vec{r}, t), \rho$$

Particle Ensemble

$$m_i, \tau, \vec{v}_i(\vec{r}, t)$$



$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \nabla \otimes \vec{u} = -\nabla p^* + \nu \Delta \vec{u}$$

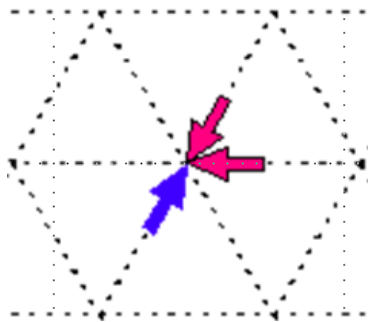
$$m_i \frac{\partial v_i}{\partial t} = \sum_{i \neq j} \frac{\partial V(\|\vec{r}_i - \vec{r}_j\|)}{\partial \vec{r}_j}$$

Wolfram 86, Hasslacher 86

Lattice Boltzmann Equation (LBE)

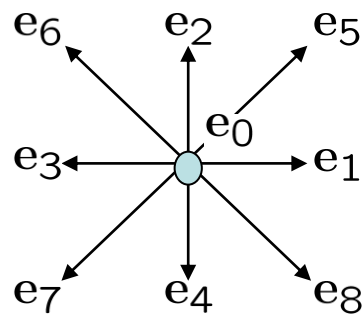
$$f_i(t + \Delta t, \mathbf{x} + \mathbf{e}_i \Delta t) = f_i(t, \mathbf{x}) + \Omega_i, \quad i = 0, \dots, b-1$$

f	Mass fractions
e	Microscopic velocity of the particles
t	Time
x	Space



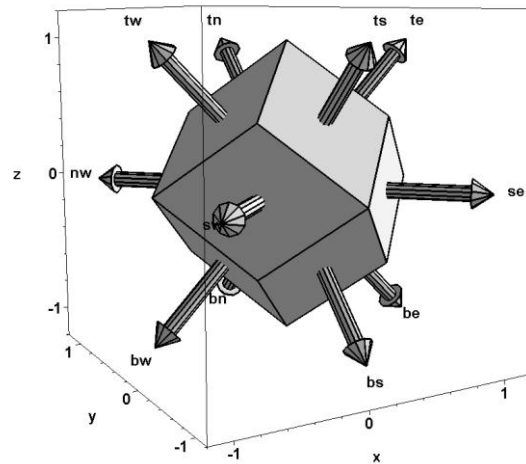
d2q6-Model

Wolfram 86, Hasslacher 86



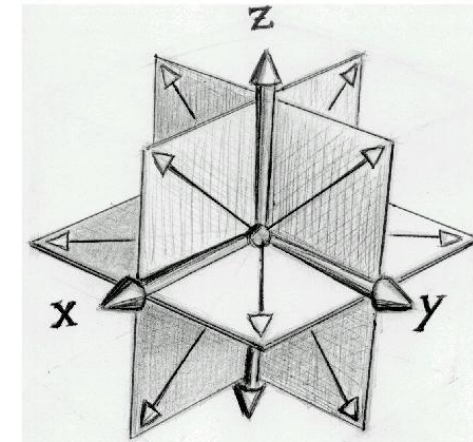
d2q9-Model

Qian 92



d3q13-Model

d'Humieres 01



d3q19-Model

Qian 92

Flow Field: Multi-Relaxation-Time model (D3Q19)

LBE: $f_i(t + \Delta t, \vec{x} + \vec{e}_i \Delta t) = f_i(t, \vec{x}) + \Omega_i(t, \vec{x})$

collision: $\Omega = M^{-1} S [m - m^{eq}]$

moments: $m = M f \quad \rho = \sum_i f_i \quad \vec{j} = \rho \vec{u} = \sum_i \vec{e}_i f_i$

$$\mathbf{m} = (\rho, e, \epsilon, j_x, q_x, j_y, q_y, j_z, q_z, 3p_{xx}, 3\pi_{xx}, p_{ww}, \pi_{ww}, p_{xy}, p_{yz}, p_{xz}, m_x, m_y, m_z).$$

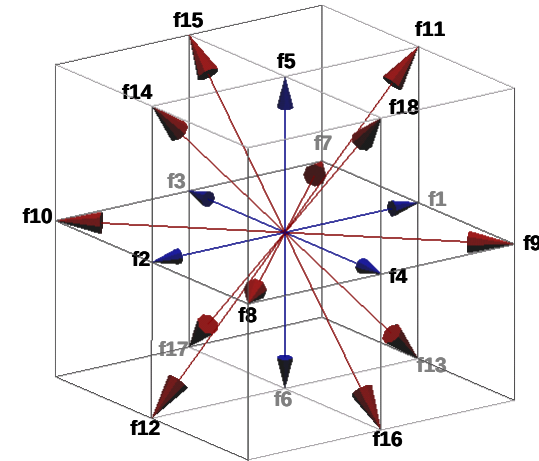
relaxation rates:

$$\{(s_9, s_{11}, s_{13}, s_{14}, s_{15})\} = -\frac{\Delta t}{\tau} \quad \tau = 3\frac{\nu}{c^2} + \frac{1}{2}\Delta t$$

$$\{(s_1), (s_2), (s_4, s_6, s_8), (s_{10}, s_{12}), (s_{16}, s_{17}, s_{18})\} \in [-2; 0]$$

equilibrium moments:

$$\begin{aligned} m_0^{eq} &= \rho \\ m_1^{eq} &= e^{eq} = \rho(3T + \vec{u}^2 - 1) \\ m_2^{eq} &= \rho(-\frac{9}{5}T + 1) \\ m_3^{eq} &= \rho u_x \\ m_5^{eq} &= \rho u_y \\ m_7^{eq} &= \rho u_z \\ m_9^{eq} &= 3p_{xx}^{eq} = \rho(2u_x^2 - u_y^2 - u_z^2) \\ m_{11}^{eq} &= p_{zz}^{eq} = \rho(u_y^2 - u_z^2) \\ m_{13}^{eq} &= p_{xy}^{eq} = \rho u_x u_y \\ m_{14}^{eq} &= p_{yz}^{eq} = \rho u_y u_z \\ m_{15}^{eq} &= p_{xz}^{eq} = \rho u_x u_z \end{aligned}$$



$$\nabla \bullet \vec{u} = 0$$

$$\frac{\partial \vec{u}}{\partial t} + \vec{u} \nabla \otimes \vec{u} + \nabla p = \nu \Delta \vec{u}$$

two-phase model:

1. two phases (red/blue)
2. generation of surface tension (capillary forces)
3. separation of phases (immiscible)

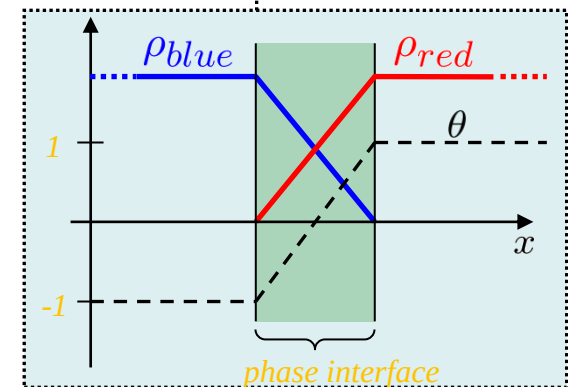
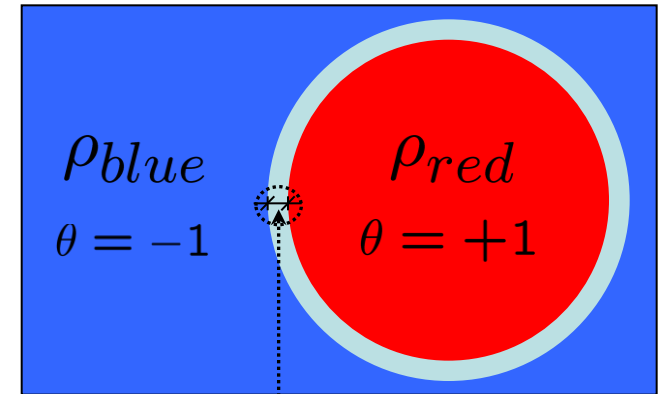
(Rothmann-Keller 1991, Gunstensen 1993)

Lattice Boltzmann extensions:

phase field:

$$\theta = \frac{\rho_{red} - \rho_{blue}}{\underbrace{\rho_{red} + \rho_{blue}}_{\rho_{\theta}}} \in [-1; +1]$$

$$\rho_{\theta} = \rho_{red} + \rho_{blue}$$

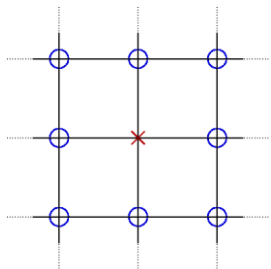


surface tension:

$$m_i^{eq,ST} = m_i^{eq} + m_i^{ST}$$

(Kehrwald, 2004 PhD, Toelke et. al., 2005)

$$\begin{aligned} m_1^{ST} &= -2 \sigma |\vec{C}| (n_x^2 + n_y^2 + n_z^2) \\ m_9^{ST} &= -\sigma |\vec{C}| (2 n_x^2 - n_y^2 - n_z^2) \\ m_{11}^{ST} &= -\sigma |\vec{C}| (n_y^2 - n_z^2) \\ m_{13}^{ST} &= -\sigma |\vec{C}| (n_x n_y) \\ m_{14}^{ST} &= -\sigma |\vec{C}| (n_y n_z) \\ m_{15}^{ST} &= -\sigma |\vec{C}| (n_x n_z) \end{aligned}$$



σ : surface tension

$\vec{C}$: gradient of phase field

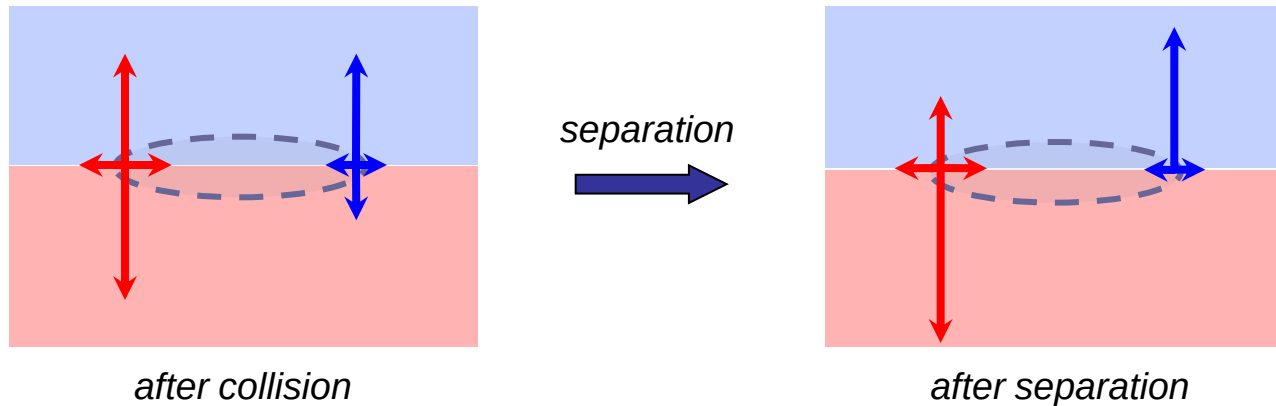
$$\vec{C}(t, \vec{x}) = \frac{3}{2 c \Delta t} \sum_i w_i \frac{\vec{e}_i}{c} \theta(t, \vec{x} + \vec{e}_i \Delta t)$$

n_α : vector normal to phase interface $n_\alpha = \frac{C_\alpha}{|\vec{C}|}$

separation:

$$\max \vec{C} \cdot j^p(\text{after separation}) = \max \vec{C} \cdot \sum_i \vec{e}_i f_i^p(\text{after separation})$$

maximum separation of phases by recoloring (optimization problem!)



advection of phase field by additional linear LBE:

$$g_i^p(t + \Delta t, \vec{x} + \vec{e}_i \Delta t) = g_i^{p,eq}(\rho_p(t, \vec{x}), \vec{u}(t, \vec{x}))$$

$$\text{with } g_i^{p,eq}(\rho_p(t, \vec{x}), \vec{u}(t, \vec{x})) = w_i \rho_p(t, \vec{x}) \left(1 + \frac{3}{c^2} \vec{e}_i \cdot \vec{u}(t, \vec{x})\right)$$

$p = \text{red, blue}$

Mass conservation:

$$\nabla \cdot \mathbf{u} = 0$$

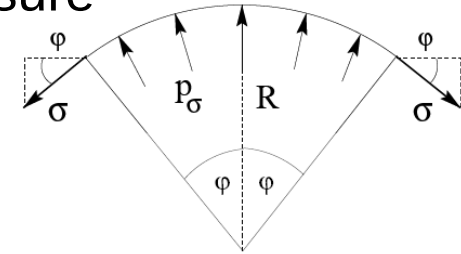
Momentum conservation:

$$\rho(\mathbf{x}) \left(\frac{\partial \mathbf{u}}{\partial t} + (\mathbf{u} \cdot \nabla) \mathbf{u} \right) = -\nabla p + \nabla \cdot (\mu(\mathbf{x})(\nabla \mathbf{u} + \nabla \mathbf{u}^T)) + \rho(\mathbf{x})\mathbf{g}$$

Interface condition:

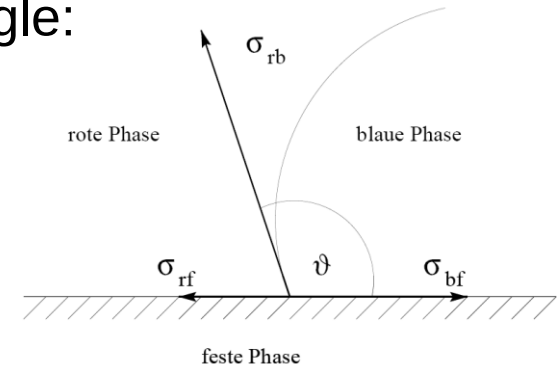
$$[\mathbf{u}]|_{\Gamma} = 0, \quad -[-p\mathbf{I} + \mu(\nabla \mathbf{u} + \nabla \mathbf{u}^T)]|_{\Gamma} \cdot \hat{\mathbf{n}} = \sigma \kappa \hat{\mathbf{n}}$$

capillary pressure



$$p_{\sigma} = \frac{\sigma}{R} = \sigma \kappa$$

contact angle:



$$\sigma_{rf} - \sigma_{bf} - \sigma_{rb} \cos \vartheta = 0$$

Comparison CPU-GPU

Intel Core i7



nVIDIA Tesla M2070



NEC SX-9A (16 CPUs)

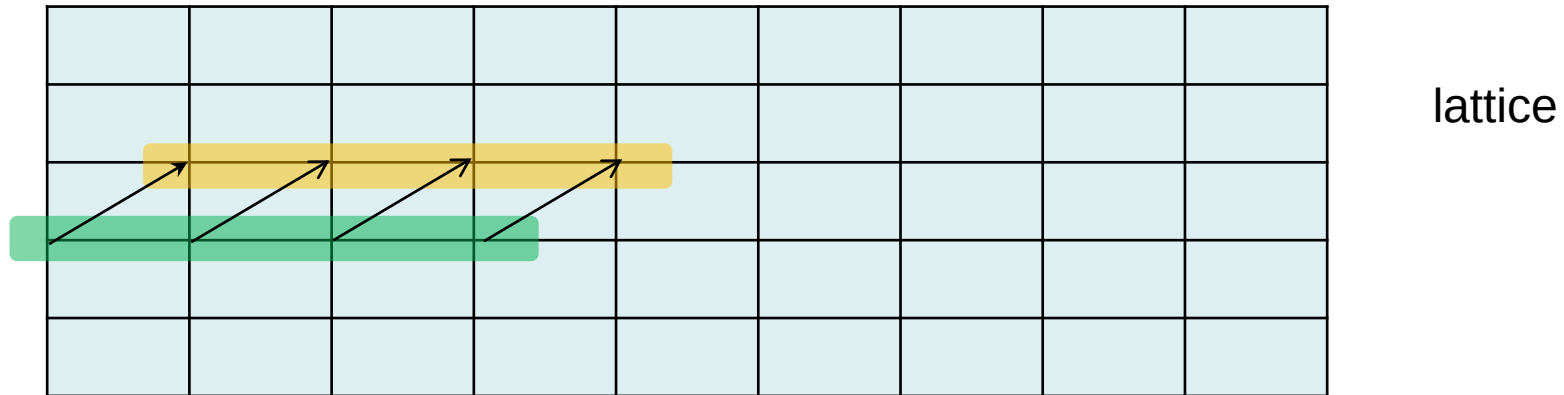


Actual Size



Platform	Memory [MB]	Peak [GFLOPS]	BW [GB/s]	price [\$]
Intel Core i7 980 XE (6 core)	24 000	80 (160 SP)	32 (15*)	ca. 4000
NEC SX-9A (16 CPUs, one node)	1 000 000	1600	4 000	expensive
nVIDIA GTX480	1 500	700 (1344 SP)	177 (120*)	ca. 500
nVIDIA Tesla M2070	6 000	515 (1030 SP)	148	ca. 4000

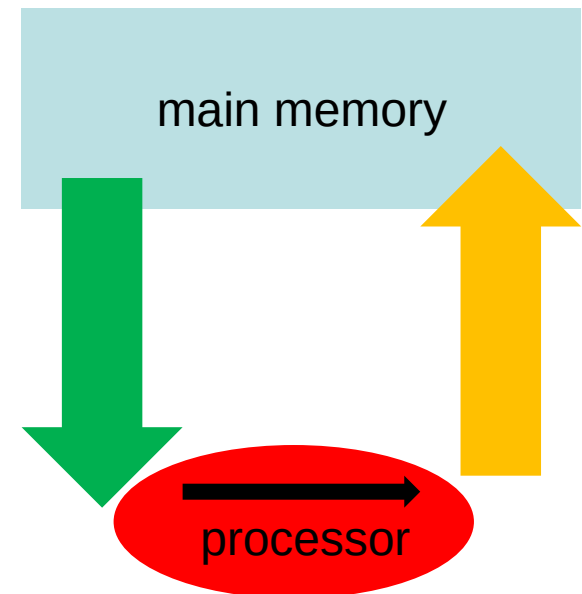
Process Collision and Propagation mapped to 'hardware'



Load data from memory (Cache Line)
Memory Bandwidth

Collision (Processor)
Peak Performance

Propagation: Write data memory (Cache Line)
Memory Bandwidth



Wellein 2006

$$P = \min \left\{ \frac{MBW}{NB}, \frac{PEAK}{NF} \right\}$$

P max. perf. in NUPS
(nodal updates per second)

MBW bandwidth bus

NB number of bytes per cell

PEAK peak performance

NF number of FLOP per cell

D3Q13

NB = (14+13) (read+write) * 4 byte (float) = 108 bytes

NF = 260 FLOP

Average Notebook: MBW = 3.5 GB/s, PEAK=8 GFLOPS

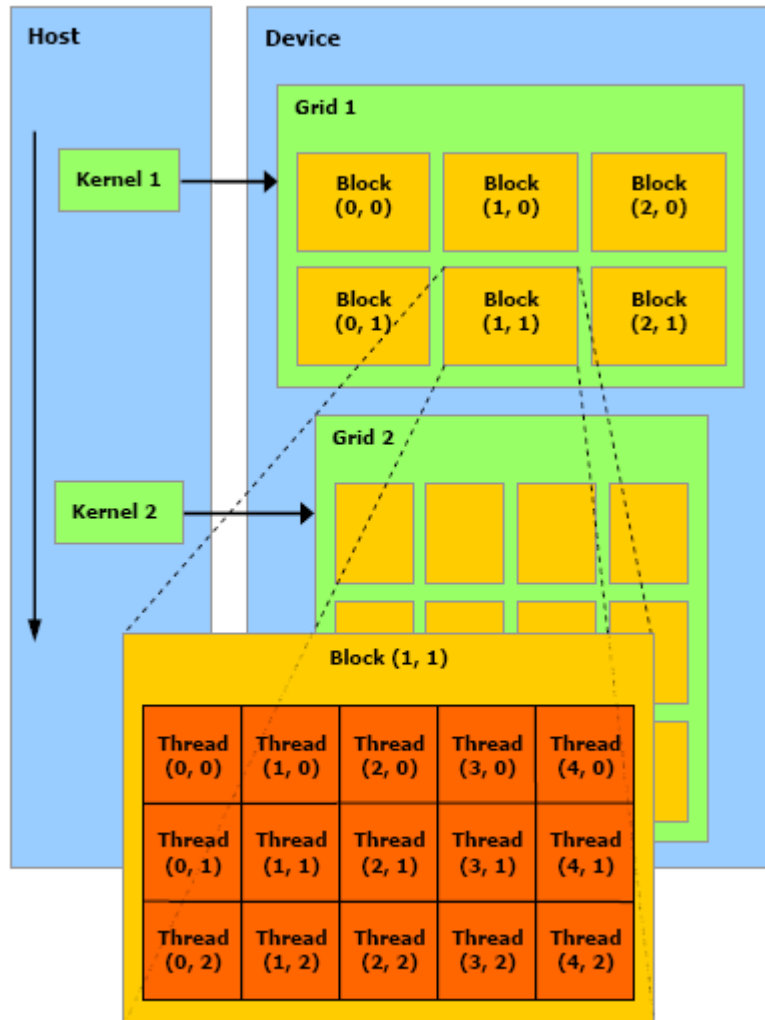
Reached:

- Limitation by **Memory Bandwidth**:
max NUPS = 3.5E9 Byte/s / 108 Byte/node
= 33 E6 NUPS

- Limitation by **Performance of CPU**:
max NUPS3 = 8.0E9 FLOPS / 260 FLOP/node
= 31 E6 NUPS

grid	MLUPS	BW	Perf.
8^3	15	-	48 %
64^3	9	27 %	29 %

Programming model: Parallelism on 2 levels

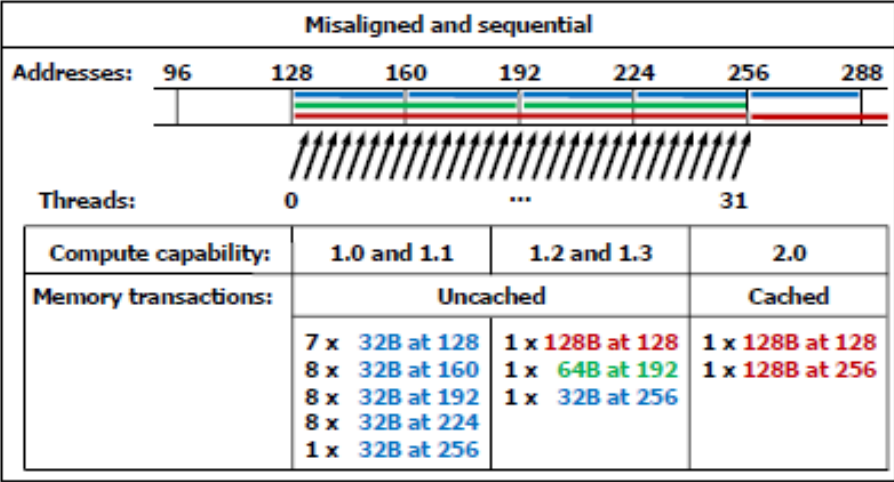
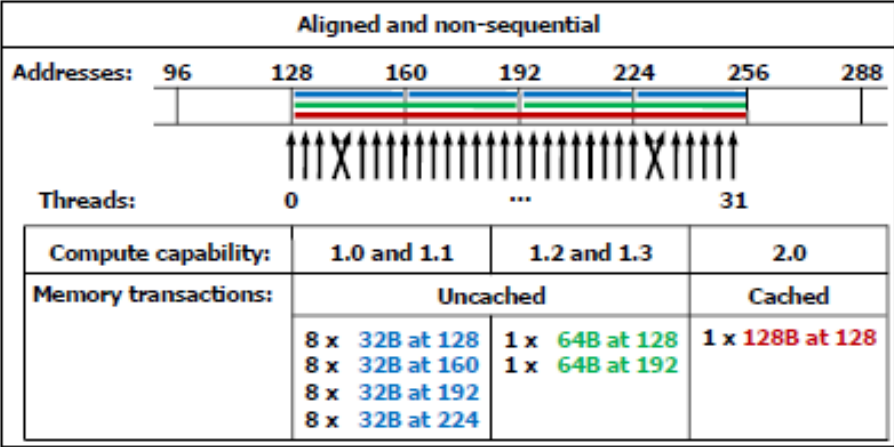
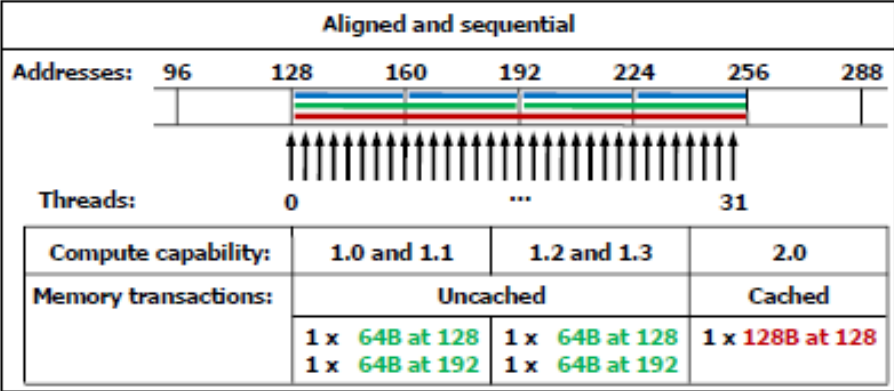


Level 1:
Grid of blocks (no communication)

Level 2:
Block of threads (shared memory)



memory access pattern



CUDA Programming
Guide

Mapping *space* location – *memory* location

Toelke et al. 2008

D3Q13 model:

Mapping 3D *space* to 1D *memory*:

$$a = \begin{cases} 0 & \text{if } j \text{ even and } k \text{ even} \\ 0 & \text{if } j \text{ odd and } k \text{ odd} \\ 1 & \text{if } j \text{ odd and } k \text{ even} \\ 1 & \text{if } j \text{ even and } k \text{ odd} \end{cases}$$

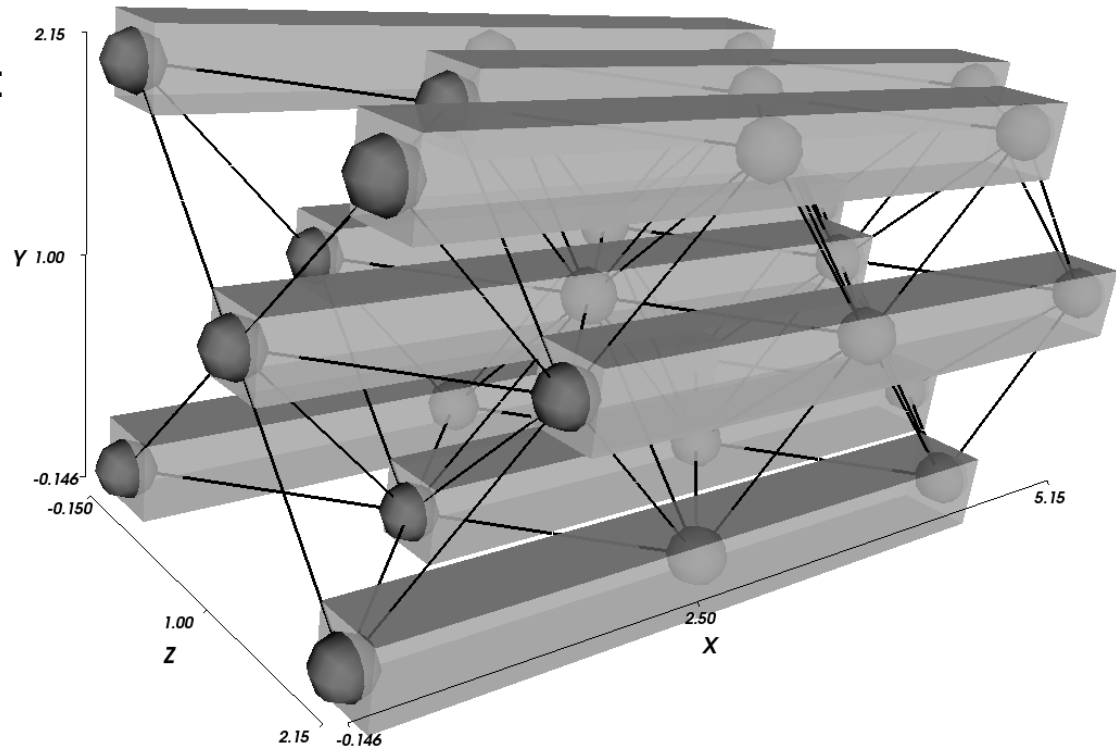
$$x = h(a + 2i)$$

$$y = h j$$

$$z = h k$$

C-Code:

```
int m = nx*(ny*k + j) + i;  
float x = h * ( (j&0x1)^(k&0x1) + i*2 );  
float y = h * j;  
float z = h * k;
```

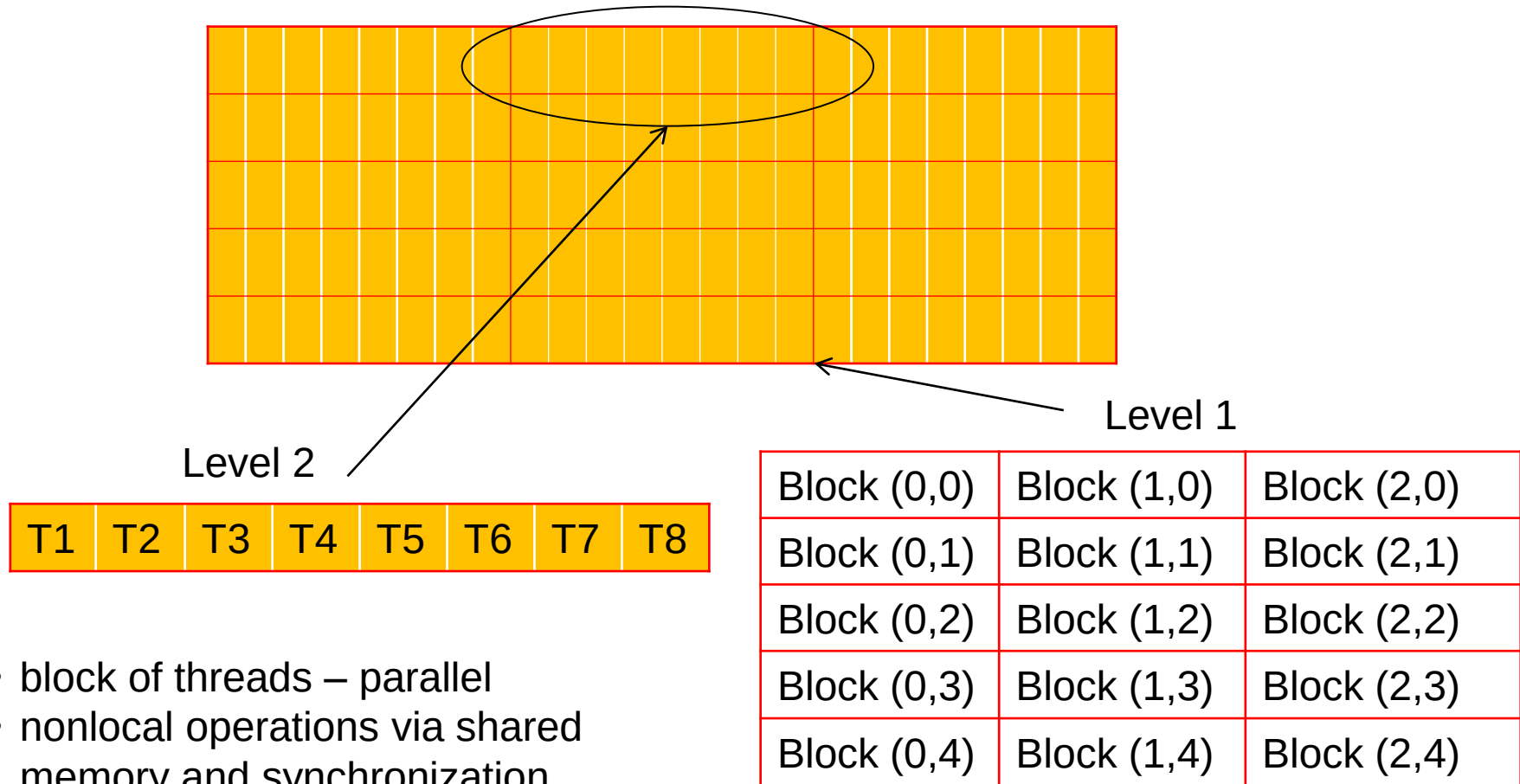


lattice size:

$2 n_x \times n_y \times n_z$ (e.g. $128 \times 128 \times 512$)

data structure:

$n_x \times n_y \times n_z$ (e.g. $64 \times 128 \times 512$)

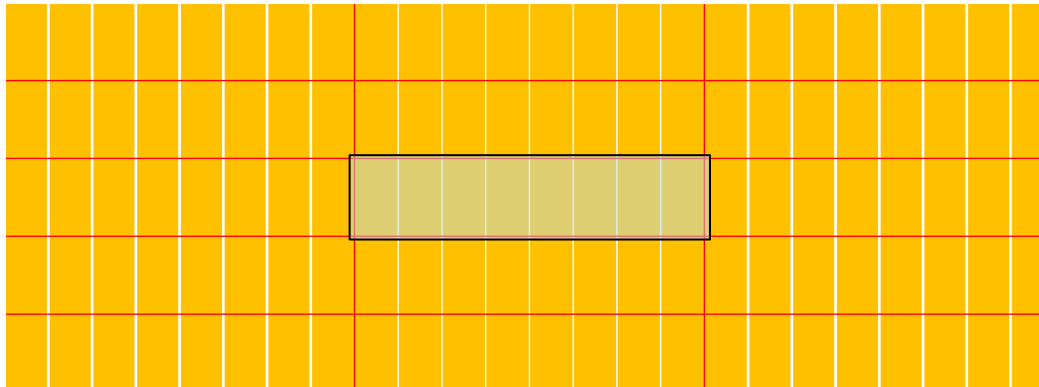


- block of threads – parallel
- nonlocal operations via shared memory and synchronization

- grid of blocks – parallel
- no communication

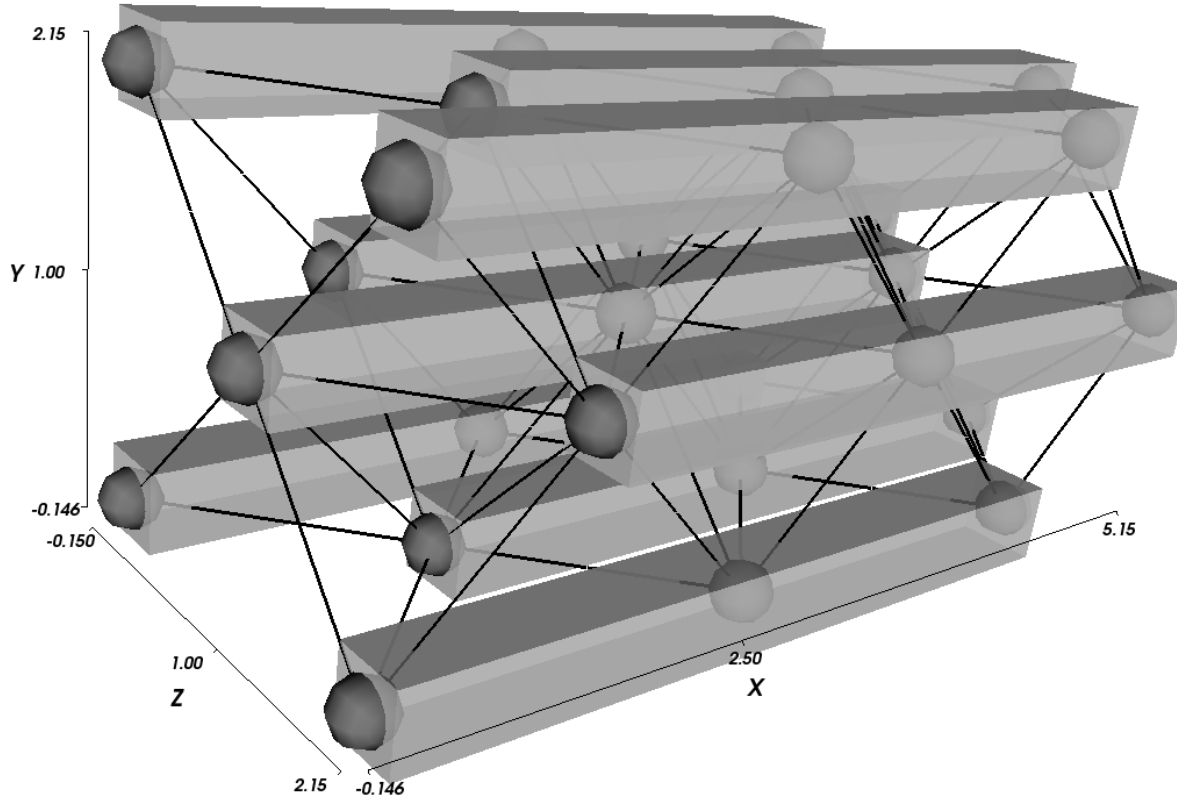
Jonas Tölke (2008): *Implementation of a Lattice Boltzmann kernel using the Compute Unified Device Architecture*, Computing and Visualization in Science, DOI 10.1007/s00791-008-0120-2

- Load streams (9 streams for d2q9)
- Complex computations (collision)
- Write streams (9 streams for d2q9) to correct address (propagation)



- north
- south
- east
- west
- northeast
- northwest
- southwest
- southeast

- x-index mapped to Threads (16-256 (32-512 lattice size))
- y- and z-index mapped to grid (at least 16 in sum)



Tölke, J. and Krafczyk, M. (2008):
***TeraFLOP computing on a desktop
PC with GPUs for 3D CFD,***
International Journal of
Computational Fluid Dynamics,
22:7, 443 — 456

simple approach with if statements

```
int nThreads = nx;  
int nBlocks.x = ny;  
int nBlocks.y = nz;  
Kernel<<< nBlocks, nThreads >>>(data,geo,...)
```

```
__global__ void Kernel(float* data, int* geo, ....)  
    int ny = gridDim.x;  
    int nz = gridDim.y;  
    int x = threadIdx.x;  
    int y = blockIdx.x;  
    int z = blockIdx.y;  
  
    int m = nx*(ny*z + y) + x;  
    if(geo[m]==FLUID) {  
        // do average work  
    }  
    else if(geo[m]==BOUNDARY){  
        // do almost nothing  
    }  
    else if(geo[m]==SOLID){  
        // do nothing  
    }  
    ....
```

Optimize:

- Eliminate if statements
- Launch only elements in parallel which have about the same work load

Increase in computational speed 2

Preprocessing: build a list for each node type

Compute capability ≥ 1.2

```
vector fluidNodes, boundNodes;
int a,b;  a=0; b=0;
```

Preprocssing

```
for(k=0 ; k<nz ; k++){
  for(j=0 ; j<ny ; j++){
    for(i=0 ; i<nx; i++){
      m = nx*(ny*k + j) + i;
      if(geo[m]==FLUID) {
        fluidNodes[a] = m;
        a++;
      }
      else if(geo[m]==BOUNDARY){
        boundNodes[b] = m;
        b++;
      }
    }
  }
  .....
}
```

Kernel calls

```
int nThreads = 64;
int nBlocks = 32;
iter = (nFluid +nThreads*nBlocks-1)/(nThreads*nBlocks)
KernelFluid<<< nBlocks, nThreads >>>(iter, nFluid, fluidNodes,...)
....
KernelBound<<< nBlocks, nThreads >>>(...
```

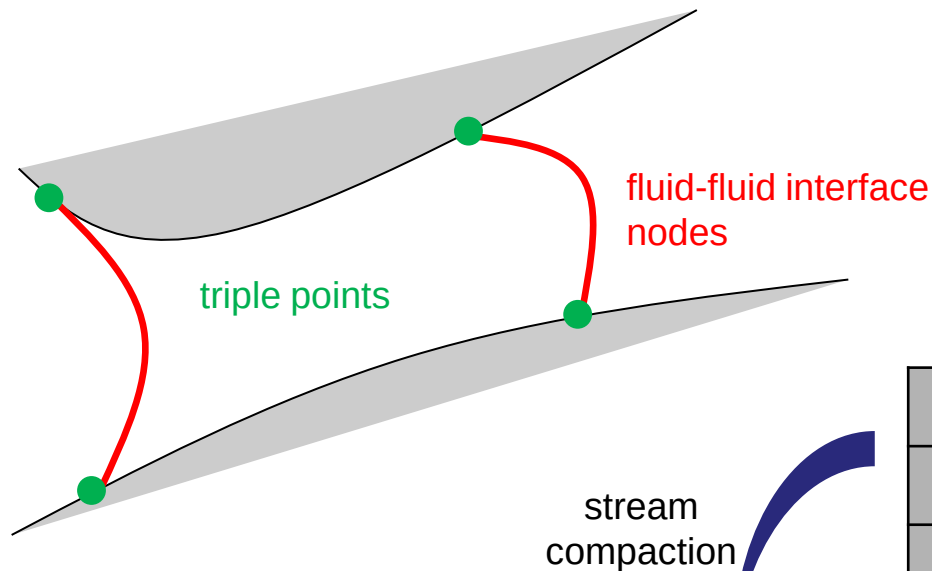
Kernel for each fluid type

```
__global__ void KernelFluid ( int iter, int  nFluid,
                               list fluidNodes,...){

  int numThreads = blockDim.x;
  int numGrid = gridDim.x;
  int tx = threadIdx.x;
  int bx = blockIdx.x;
  for(int iloop=0; iloop<iter; iloop++){
    l = numThreads*(iloop*numGrid+bx)+tx;
    if(l >= nCompute ) break;
    m = fluidNodes[l];
    .....
  }
}
```

```
__global__ void KernelBound(.....
```

Increase in computational speed 3



list of points changes each time step

use (dynamic) stream compaction (cudpp) to generate the lists at each time step

CUDPP: CUDA Data Parallel Primitives Library

- parallel prefix-sum ("scan"), sort, reduction.
- stream compaction
- building data structures such as trees and summed-area tables

Mark Harris, Shubhabrata Sengupta, and John D. Owens. "Parallel Prefix Sum (Scan) with CUDA". In Hubert Nguyen, editor, GPU Gems 3, chapter 39, pages 851–876. Addison Wesley, August 2007

computational grid

1	2	3	4	5	6
7	8	9	10	11	12
13	14	15	16	17	18
19	20	21	22	23	24

list triple points nodes

2	4	19	22
---	---	----	----

list interface nodes

8	9	11	14	17
---	---	----	----	----

Reduction of memory consumption 1

sparse data structure 1:

`f[0..8, nnodes]:`

a list for mass fractions at computational nodes only

`memLoc[nx*ny]:`

a full matrix of the memory locations for the mass fractions, needed for operations involving neighbors

`computeNodes[nnodes]:`

a list of the location of compute nodes within `memLoc`

memory: $(9+1) * nnodes + nx * ny =$
 $(10 * porosity + 1) * n$

- for porosities between 20% and 80 % good reduction in memory consumption
- memory consumption goes not to zero if porosity goes to zero
- computing of neighbor index in `memLoc` is needed for each access

geo-matrix + enumeration (temporary):

1	2	3	4	5	6
7	8	9	10	11	12
13	14	15	16	17	18
19	20	21	22	23	24

`memLoc:`

-1	-1	1	-1	-1	-1
-1	-1	2	3	-1	-1
-1	-1	4	5	-1	-1
-1	-1	-1	6	7	-1

`computeNodes:`

3	9	10	15	16	22	23
---	---	----	----	----	----	----

M. Schulz, J. Tölke, M. Krafczyk, E. Rank: Parallel single- and multiphase CFD-applications using lattice Boltzmann methods. *Transactions of the first joint HLRB and KONWIHR status and result workshop*, Springer. 91-103 (2003)

Reduction of memory consumption 2

sparse data structure 2

$f[0..8, \text{nnodes}]$

a list for mass fractions at computational nodes only

$\text{neighbors}[0..7, \text{nnodes}]$

a list of all neighbors

memory: $(9+8) * \text{nnodes} = 17 * \text{porosity} * n$

direct access to neighbors

memory consumption goes to zero if porosity goes to zero

for porosities 50 % and greater no reduction or even increase in memory consumption

$$(10 * \text{porosity} + 1) = 17 * \text{porosity}$$

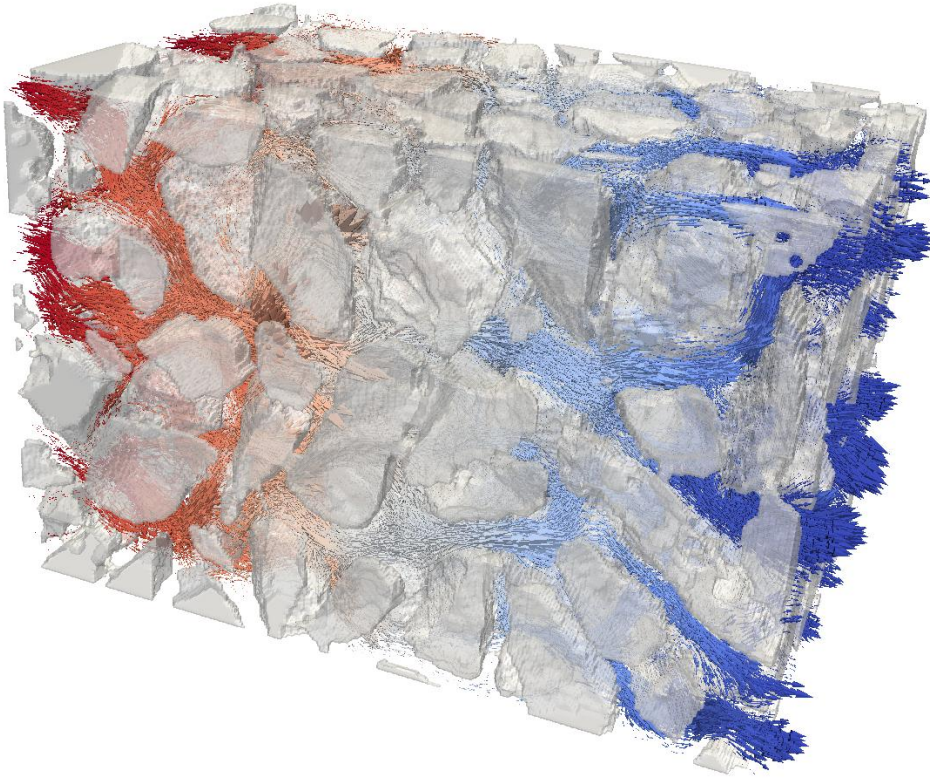
$$\text{porosity} = 1/7$$

memLoc (temporary):

-1	-1	1	-1	-1	-1
-1	-1	2	3	-1	-1
-1	-1	4	5	-1	-1
-1	-1	-1	6	7	-1

neighbors:

e	-1	3	-1	5	-1	7	-1
n	-1	1	-1	2	3	5	-1
w	-1	-1	2	-1	4	-1	6
s	2	4	5	-1	6	-1	-1
ne	-1	-1	-1	3	-1	-1	-1
nw	-1	-1	1	-1	2	4	5
sw	-1	-1	4	-1	-1	-1	-1
se	3	5	-1	6	7	-1	-1

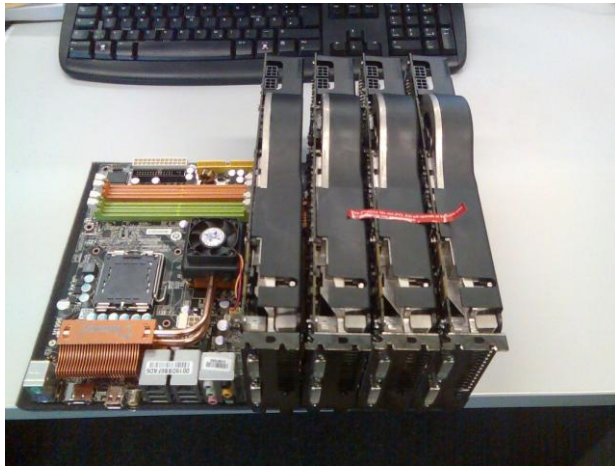


Darcy's law:

$$q = -\frac{k}{\mu} \nabla P$$

- sandstone
- porosity=30%
- sparse data structure 1
- size=200*200*300
- single phase D3Q13 model
- GTX 480, FERMI

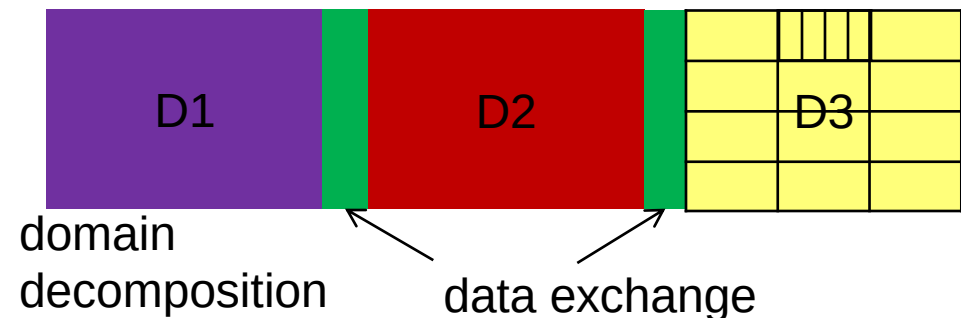
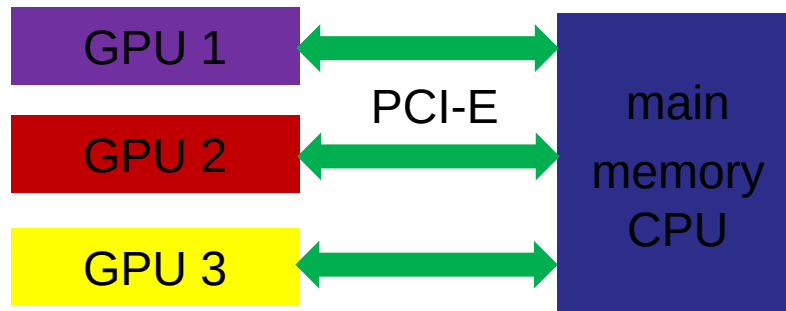
	Throughput in GB/s
DeviceToDeviceCopy	118
LB full matrix, only fluid	80
sandstone, sparse	55



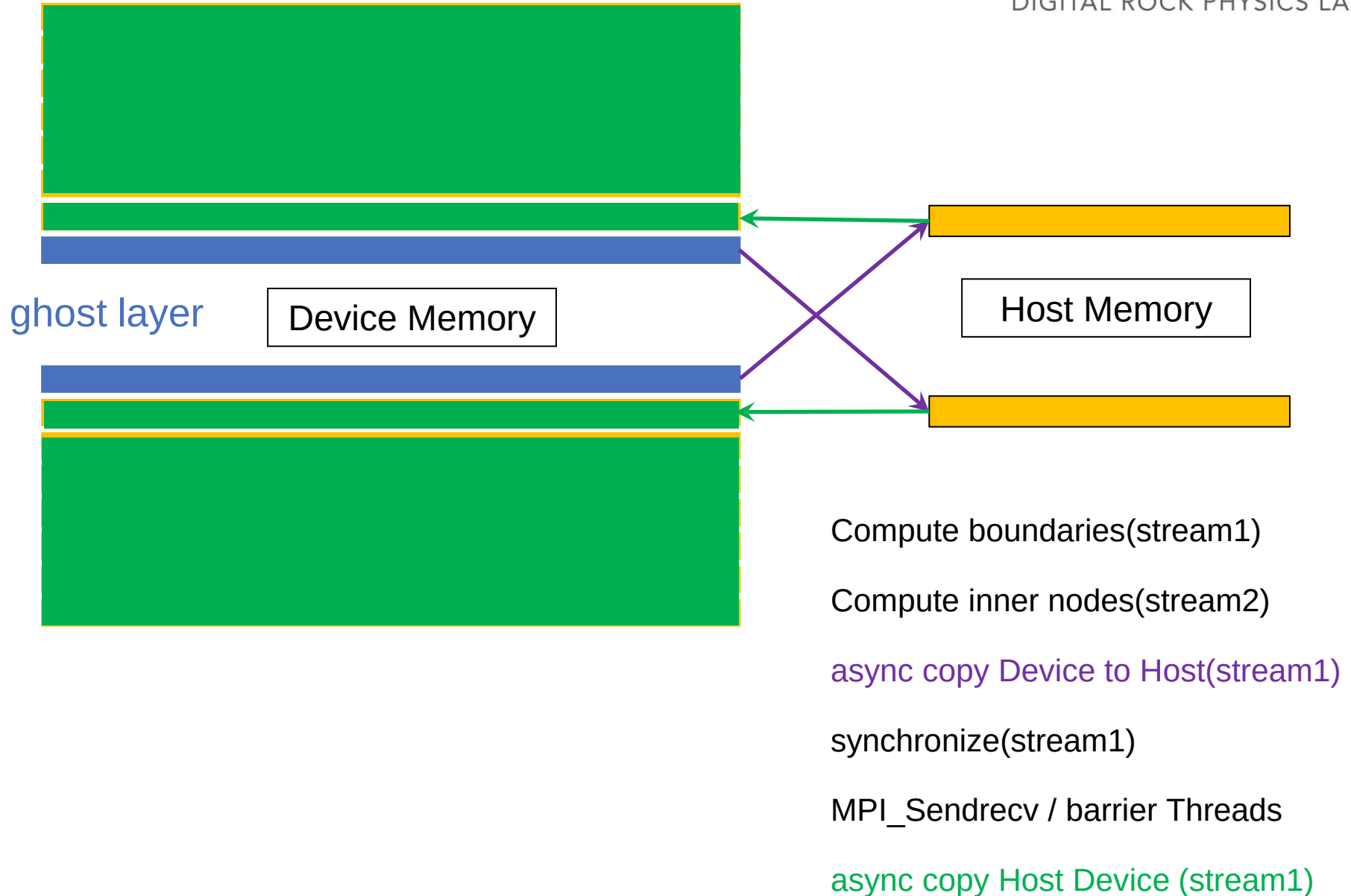
Communication between GPUs:

- PCI-E
- Latency like Front Side Bus (e.g. 266 MHz)
- **PThreads**
- **CUDA**

	Bandwidth [GB/s]	Latency [ns]
PCI-E2.0(x16)	8.0	O(100)
Infiniband QDR 4X	3.2	1 000
10G-Ethernet	1.25	5 000



Multi-GPU: communication hiding with streams



Multi-GPU: relation parallel efficiency and bandwidth

- Assuming Communication Hiding with Comp. Cap. ≥ 1.2
- Application performance limited by bandwidth
- Bandwidth GPU: $BW_g \text{ O}(100\text{GB/s})$
- Bandwidth PCI-E: $BW_p \text{ O}(5\text{GB/s})$
- Bandwidth Infiniband: $BW_i \text{ O}(1\text{GB/s})$

Within one node: Pthreads+PCI-E

Several nodes: MPI+Infiniband

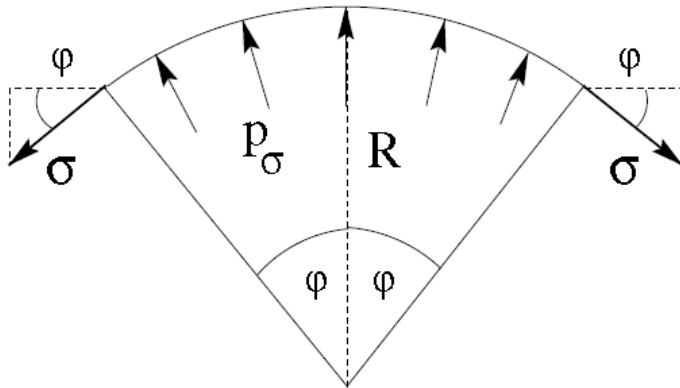
Domain decomposition: Slices in x

Minimum size of sub-domain in x: $x/2 = BW_g/BW_{p,i} \rightarrow x=40,200$

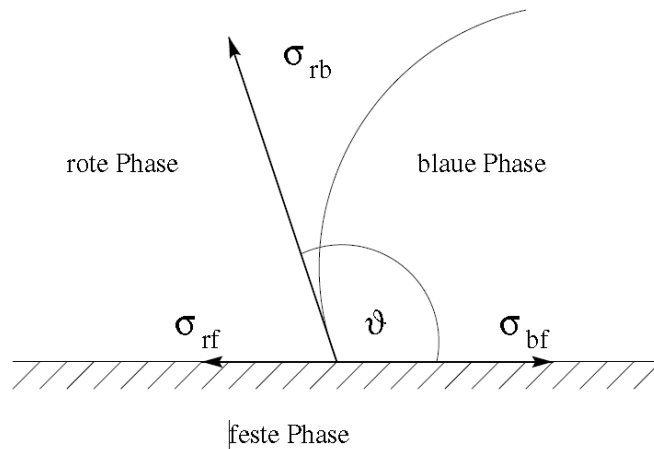
Domain decomposition: Cubes

Minimum edge length $n^3/(6*n^2) = BW_g/BW_{p,i} \rightarrow n=120,600$

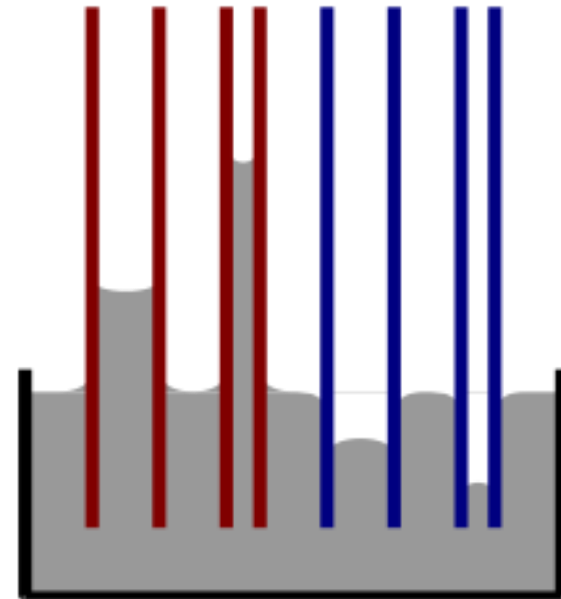
Capillary pressure 1



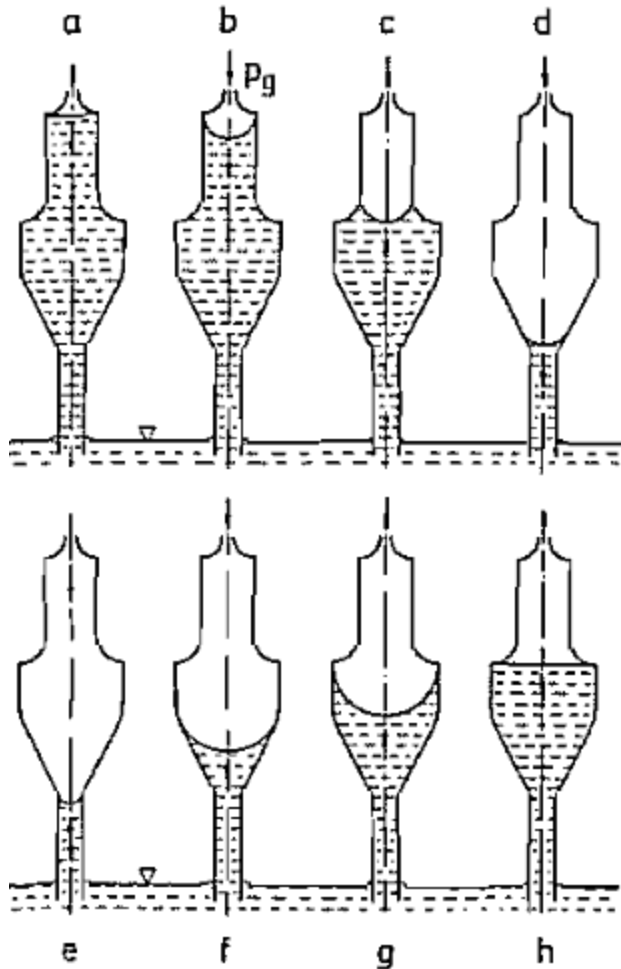
interfacial tension ρ
capillary pressure $p = \sigma/R$



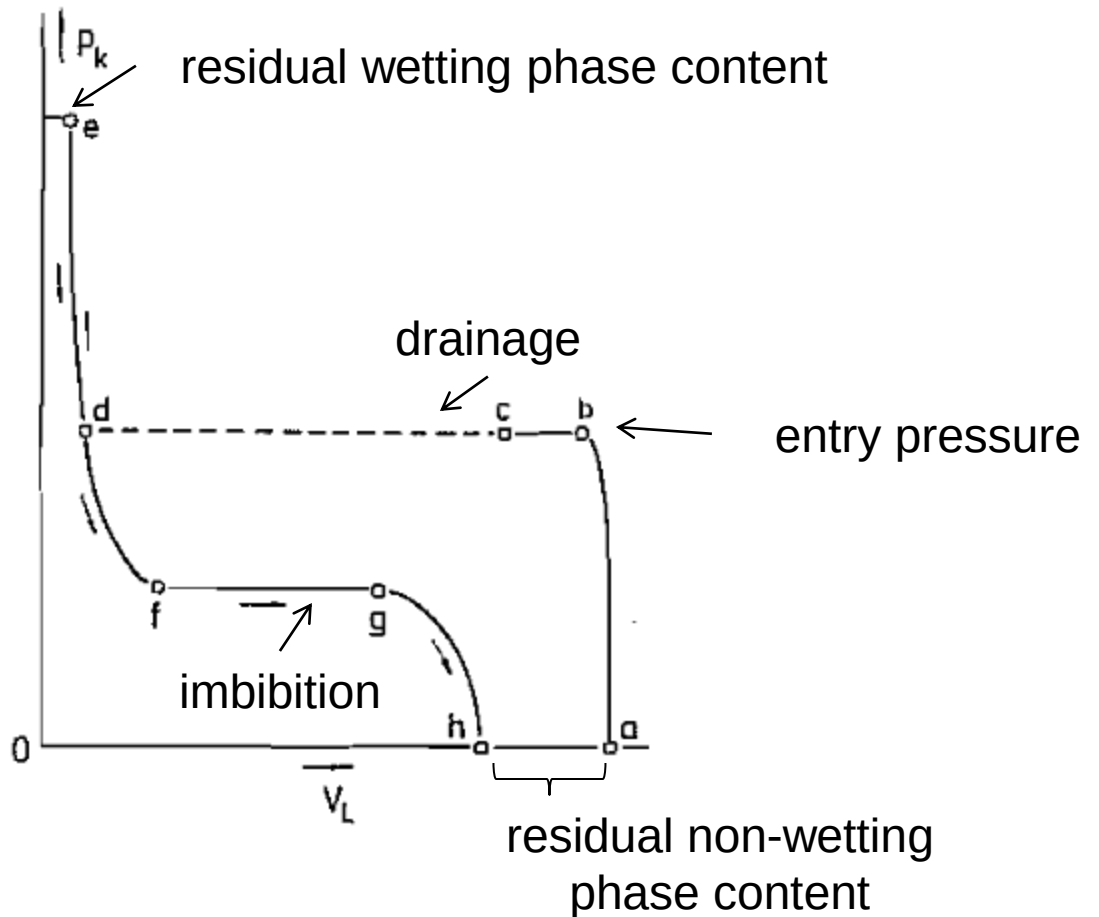
contact angle



capillary rise

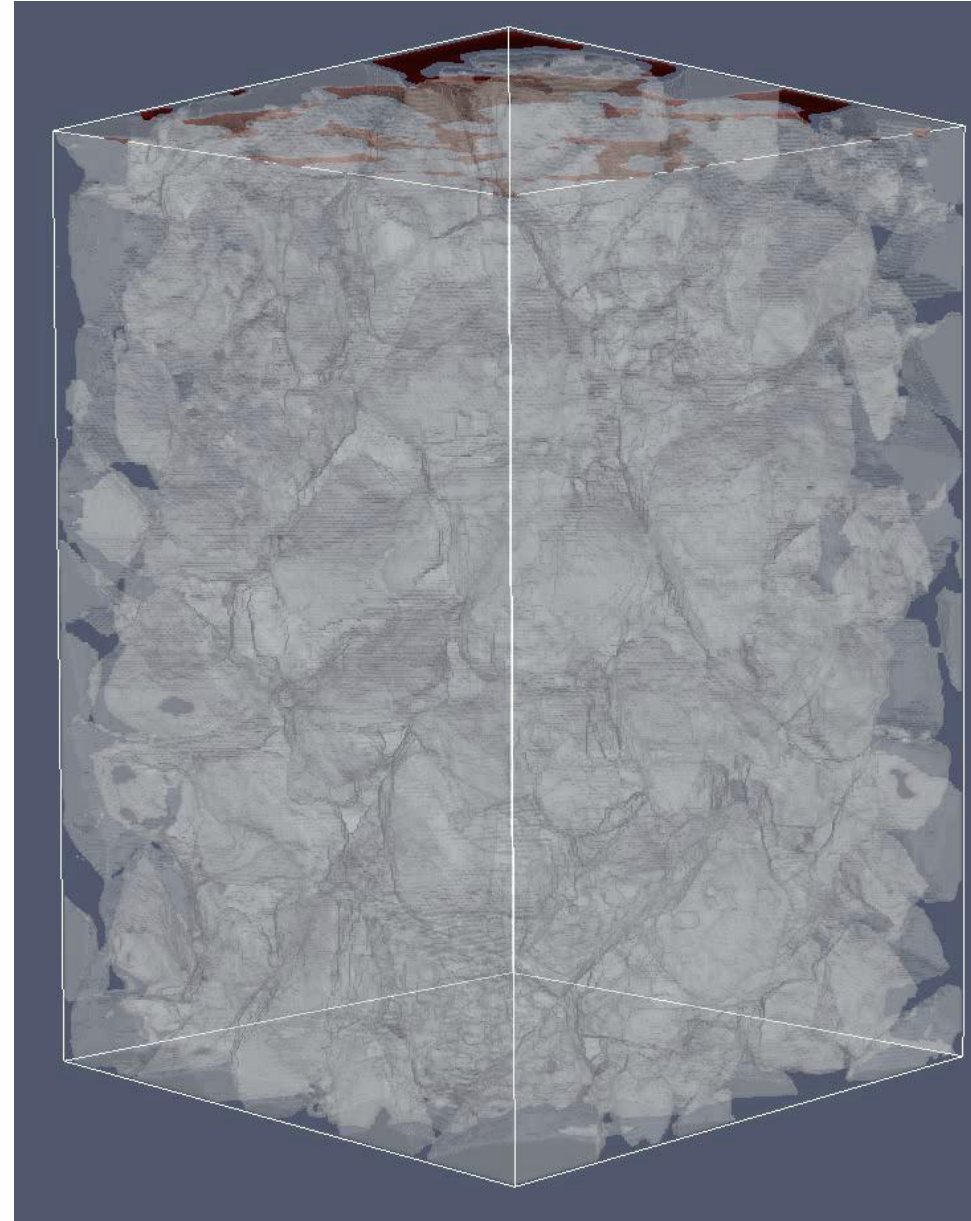
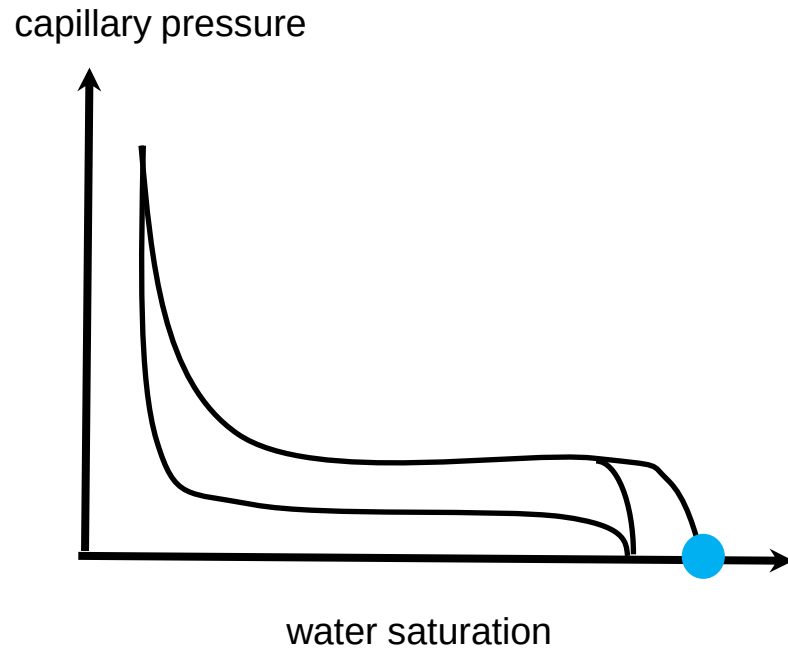


Schubert 1982



Numerical Experiments: Drainage-Imbibition

- sandstone
- LB multiphase-model
- Sparse grids

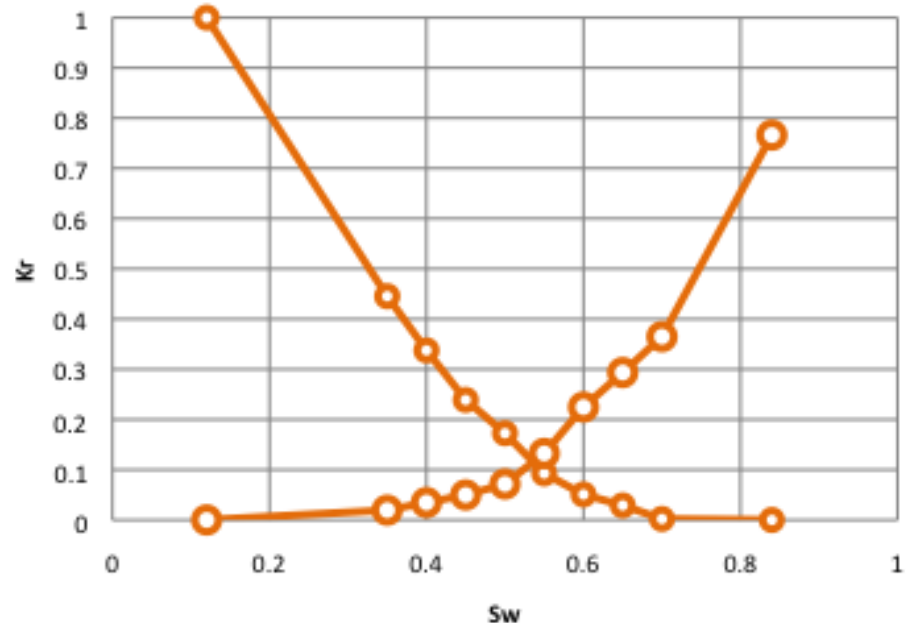


- two phases: Darcy's law has to be extended.
- second phase acts like an additional obstacle to the other phase and reduces though the permeability.

$$q = -\frac{k}{\mu} \nabla P$$

$$q_o = -\frac{k \, k_{ro}(S_w, Ca)}{\mu_o} \nabla P$$

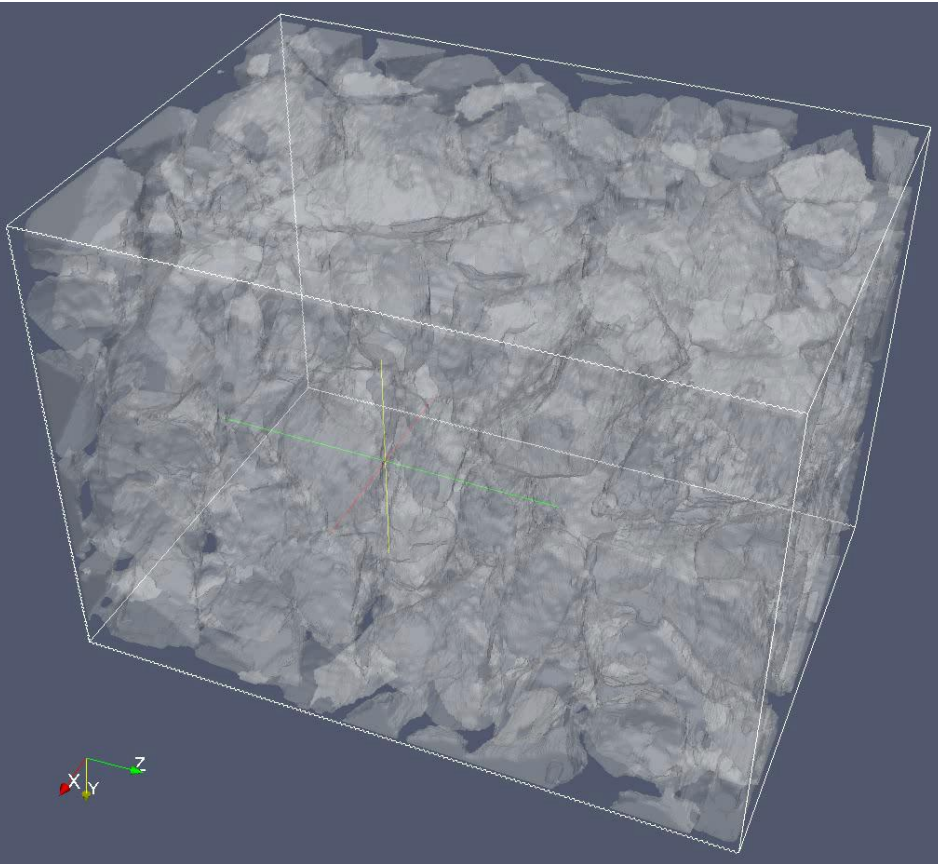
$$q_w = -\frac{k \, k_{rw}(S_w, Ca)}{\mu_w} \nabla P$$



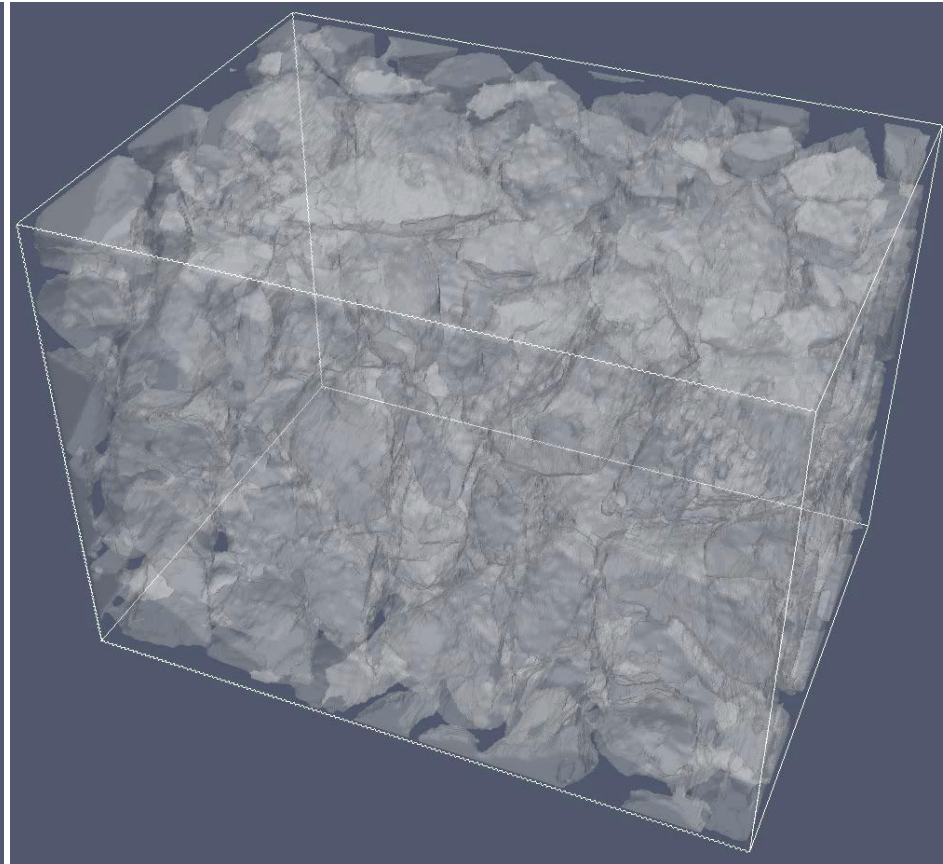
relative permeability sandstone

fractional flow: flow of water and oil simultaneously

- LB multiphase-model
- Sparse grid

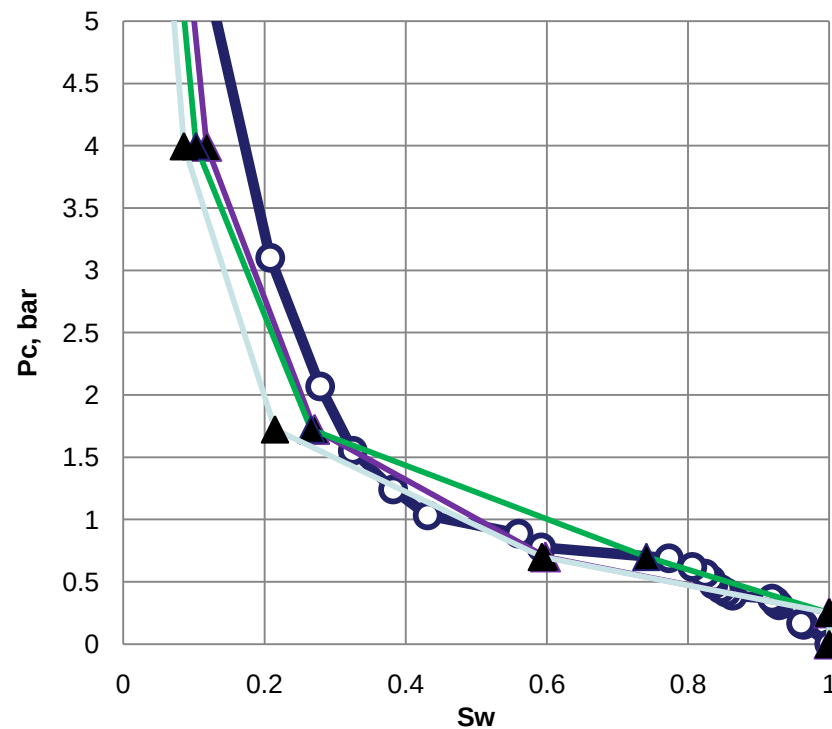
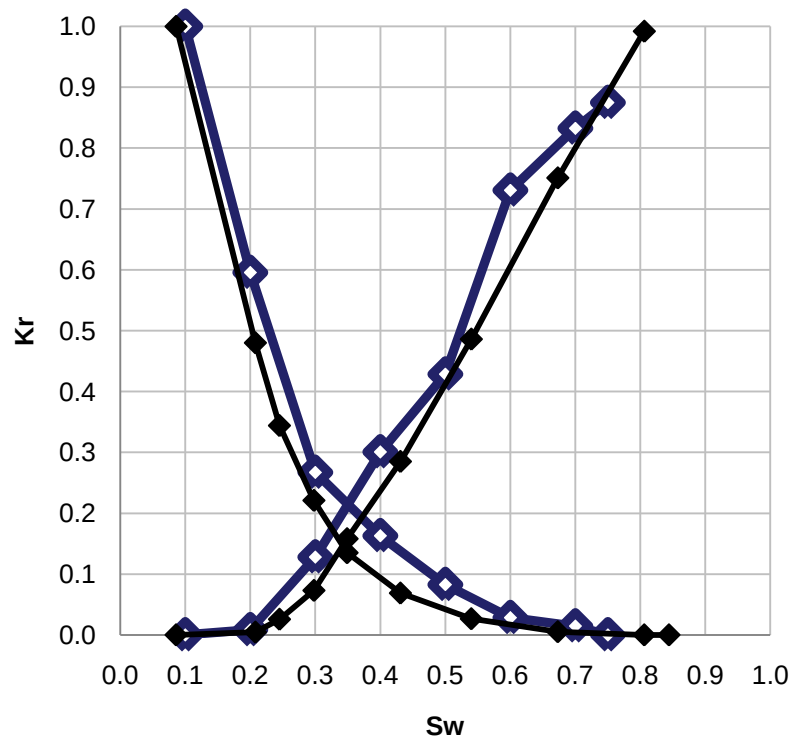


high Capillary number



low Capillary number

Ingrain Data and Lab Data



AS Grader; Y. Mu; J. Toelke; C. Baldwin; Q. Fang, G. Carpio, *Ingrain*; B. Stenger; T. Al Dayyani; Z. Kalam, ADCO: ***Estimation of relative permeability using the Lattice Boltzmann method for fluid flows in a Cretaceous Formation, Abu Dhabi***, SPE-138591-PP, Abu Dhabi, UAE, November 2010, Abu Dhabi International Petroleum Exhibition & Conference.

Grader, A., Kalam, M. Z., Toelke, J., Mu, Y., Derzhi, N., Baldwin, C., Armbruster, M., Al Dayyani, T., Clark, A., Al Yafei, G. B., and Stenger, B: ***A Comparative study of DRP and laboratory SCAL evaluations of Carbonate cores***, SCA, Halifax, Oct. 2010

Toelke, J., C. Baldwin, Y. Mu, N. Derzhi, Q. Fang. A. Grader, J. Dvorkin: ***Computer simulations of fluid flow in sediment: From images to permeability***, The Leading Edge, (2010) 29, 1040-1048.

AS. Grader, Ingrain, A. B.S. Clark, ADCO, Taha Al-Dayyani, ADCO, and Amos Nur, Ingrain: ***Computations of Porosity and Permeability of Sparic Carbonate Using Multi-scale CT Images***, International Symposium of the Society of Core Analysts, Noordwijk aan Zee, The Netherlands, 27-30 September, 2009

J. Dvorkin, N. Derzhi, Q. Fang, A. Nur, B. Nur, A. Grader, C. Baldwin, H. Tono and E. Diaz: ***From Micro to Reservoir Scale: Permeability from Digital Experiments***, The Leading Edge; December 2009; v. 28; no. 12; p. 1446-1452

- **1 GPUs = 10 powerful Pc's**
- Dollar/FLOP (CHEAP) and WATT/FLOP (**Green Computing**) very favorable
- No tedious access to supercomputers (data transfer)
- telsa hardware is robust and running very stable.
- L2 cache in Fermi allows for more complicated data structures and irregular access:
 - Nonlocal operations easier
 - mesh refinement
- **Digital rock physics works**
- **Direct solution of two-phase flow in the pore structure**
- **Direct computations – no calibration**
- **Reproducible results**
- **parameter studies**
- **Fast**

Conclusions

- **nVIDIAS GPUs and CUDA helped Ingrain to bring down the cost and time for complex fluid flow simulations in real rocks.**



Abu Dhabi Lab
Opened June 2010
10,000 sq feet