CUDA Acceleration of Color Histogram Matching Antonio S. Montemayor, Raúl Cabido, Juan José Pantrigo Xavi Rodríguez, Sergi Sàgas Universidad Rey Juan Carlos, SPAIN

A common approach to histogram matching is done by means of the cumulative distribution functions (CDFs). First, we calculate their normalized histograms (h_A and h_B) and their respective cumulative histogram distribution functions (CDF_A and CDF_B). Then, a matching between the CDFs are performed. Given the reference CDF, CDF_A, for each gray level G_i we find the corresponding gray level G_j in which $CDF_A(G_i) = CDF_B(G_j)$, if I and J correspond to different values then a replacement of a gray level in the image IB is performed in order to match their CDFs. Our approach considers the ideas of [Rolland et al. 2000] with a Nvidia 3D broadcast solution system using professional HD cameras. ROLLAND, J. P., VO, V., BLOSS, B., AND ABBEY, C. 2000. Fast algorithms for histogram matching: Application to texture synthesis. Journal of Electronic Imaging 9(1).



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Reference Image (A) CDFs are monotonically nondecreasing Luminance modified (B) Error (x5) functions. Each thread in CDF_A evaluates CDF_B until $CDF_A(G_I) = CDF_B(G_J)$, creating a LUT with new color values in 0-255 color indices. *\$* Each original CDF_B color in B(x,y) is Histogram changed matching according to the previous LUT, creating $B_2(x,y)$ Error (x5) Result Image (B_2) ትት ትትትት ትትትት ትትትት ትትትት ትትትት ትትትት 575 5555 5555 5555 5555 5555 5555 5555 CONCLUSION **1920x1080** 3648x2736 Histogram techniques are not very parallel friendly, (HD) however we found very useful the 1.2 compute capability feature of atomic operations on CUDA 49 ms 207 ms shared memory to improve about x20 the performance of histogram computation on GPU (compared to global 104 ms 29 ms memory usage). Overall, for the histogram matching problem, we get about x5.2 performance 52 ms 9.5 ms improvement compared to CPU execution enabling real time (>30 fps) processing on HD imagery (1920x1080) for possible 3D content creation and accurate depth estimation.







