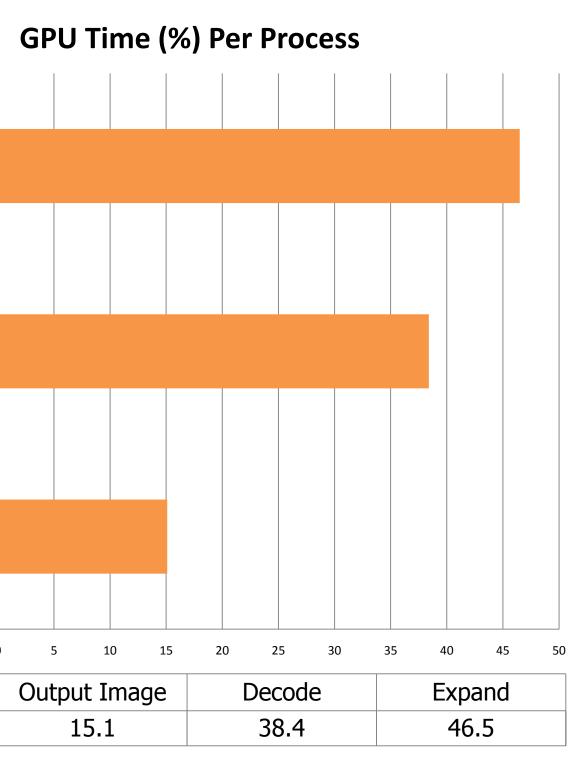


GPU-accelerated Texture Decompression of Biomedical Image Stacks Chirantan Ekbote^{1,2}, Won-Ki Jeong¹, Jens Schneider³, Hanspeter Pfister¹ ¹School of Engineering and Applied Sciences, Harvard University ²Department of Computer Science and Engineering, The Ohio State University

Decompression Reconstruction of the images is then 2 x 2 Expand accomplished by simply reversing the encoding process: 1. Fetch the 2x2 pixels for the top and bottom images and linearly interpolate the values to get the desired slice. 32 x 32 2. Expand the image to 32x32 pixels. 3. Fetch and incorporate the encoded differences into the predicted image. 4. Repeat step 3 once by expanding the image to 128x128 pixels and once more by expanding to 512x512 pixels. 128 x 128 Expand GPU Time (%) Per Process Expand Decode Output Image 512 x 512 Expand Decode Output Image GPU Time (%) 38.4 46.5 15.1Figure 4: Overview of the stages of decompression (left) and GPU time for each decompression stage (right). Results **CPU vs. GPU:** Decoding a single slice on the GPU was more than **36x** faster than on an 8-core CPU. This is because the highly parallel architecture of the GPU enables decoding of blocks of pixels together, significantly reducing computation time. **Decoding Time** 512 x 512 x N Single Core CPU 8-Co Decoding Time 162.93

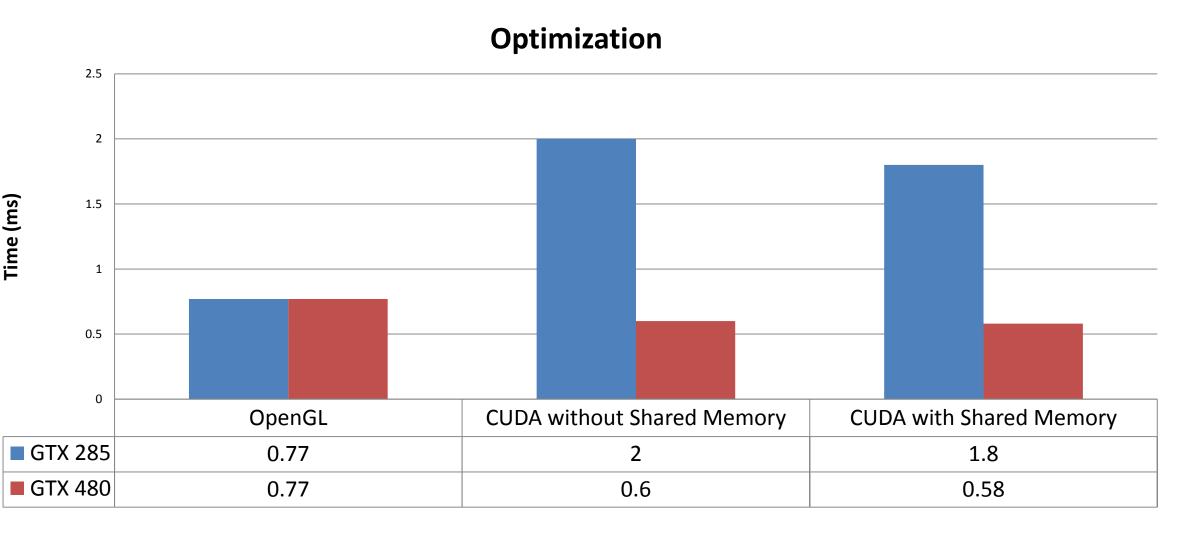
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ore CPU	GPU
1.16	0.58

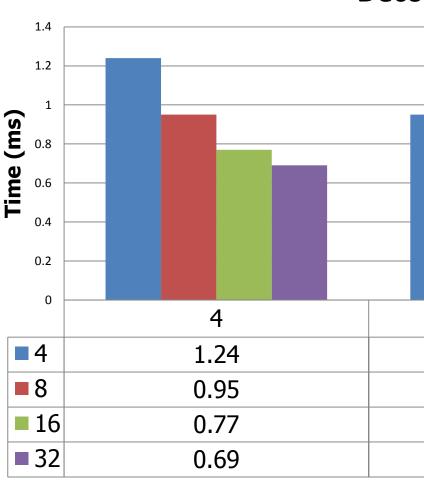
OpenGL vs. CUDA / GTX 285 vs. GTX 480:

• Decoding time for a single slice using OpenGL was same on the GTX 285 and 480, although CUDA performance was much worse on the 285. • Using shared memory provided a **10%** increase in speed over using global memory on the GTX 285. • Decoding a single slice on the GTX 480 was **24%** faster using CUDA than using OpenGL, mainly due to the efficient memory management and the L1/L2 hardware cache. A side effect of having the cache was that using shared memory provided no significant advantage over using global memory.



Kernel Block Dimensions:

• Decoding times were recorded for varying thread block dimensions of each kernel call from 4x4 threads per block to 32x32 threads per block. • Empirically, we found that using a block size of 16x16 threads per block was ideal for our implementation.



Summary: We have created a tool for pathologists to visualize large highresolution optical microscopy image stacks at interactive rates. This is accomplished by a novel variation on predictive hierarchical vector quantization that can be fully decoded on the GPU.

Future Work: Test and implement the compression algorithm and decoder for electron microscopy data to incorporate it into a framework for semi-automatic segmentation and visualization of neural processes.

[1] Won-Ki Jeong, Jens Schneider, Stephen G. Turney, Beverly E. Faulkner-Jones, Dominik Meyer, Rüdiger Westermann, Clay Reid, Jeff Lichtman, Hanspeter Pfister, Interactive Histology of Large-Scale Biomedical Image Stacks, IEEE Transactions on Visualization and Computer Graphics, 2010 (to appear).

0.69 0.95 0.77 0.7 0.61 0.6 0.58 0.6 0.6 0.61 0.6 0.7

Decoding Time By CUDA Thread Block Size

Conclusion

References