

# Massively Parallel Incompressible Navier-Stokes Computations on the NCSA Lincoln Tesla Cluster

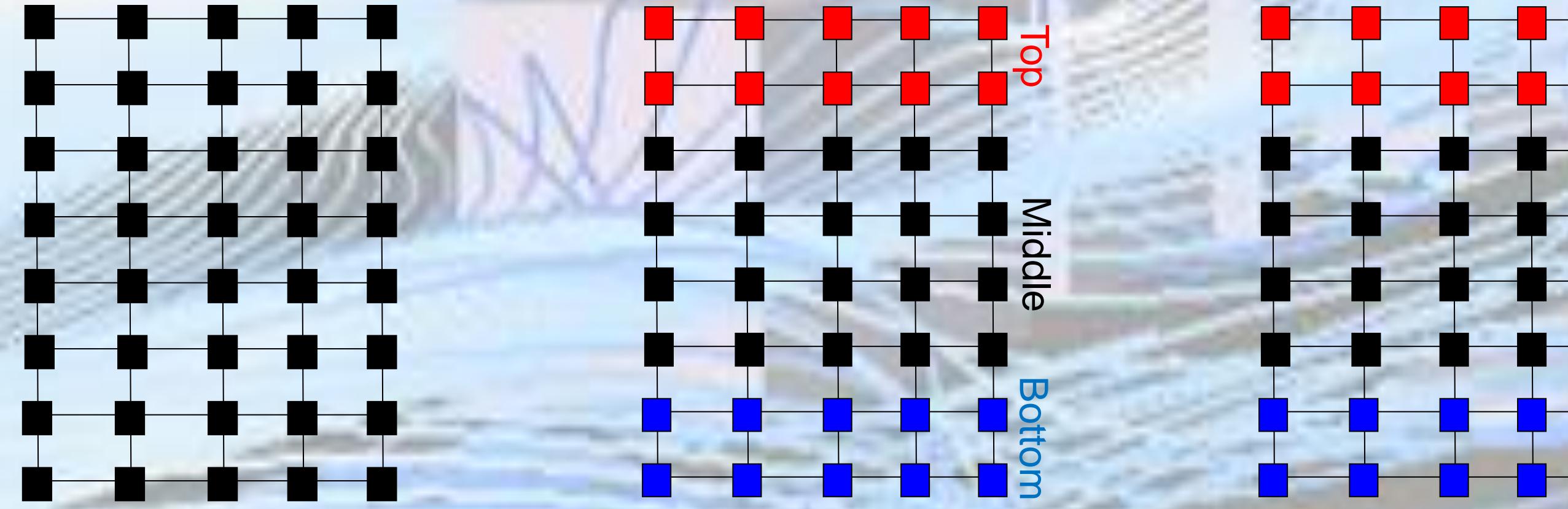
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**Objective:** Develop a *scalable* and *efficient* incompressible Navier-Stokes solver for emerging massively parallel *multi-GPU* clusters

## Pseudocode MPI+CUDA Implementation

```
for (timestep = 1 .. ntimesteps) {
    temperature<<< u,v,w,phi >>>
    Copy_Exchange_Ghost_Cells(phi)
    momentum<<< u,v,w,phi >>>
    Obstacle_Logic
    Copy_Exchange_Ghost_Cells(u,v,w,p)
    divergence<<< u,v,w,div >>>
    for (jacobisteps = 1 .. Iterations) {
        pressure<<< div, p >>>
        Copy_Exchange_Ghost_Cells(p)
    }
    velocity_correct<<< u,v,w,p >>>
    Obstacle_Logic
    Copy_Exchange_Ghost_Cells(u,v,w)
}
```

## Copy/Exchange Strategies



### No Overlap

- Compute full domain
- Copy and send top/bottom using MPI async calls
- Finish MPI receives, copy top/bottom to device

### Overlap

- Compute top
- Compute bottom
- Copy top/bottom to host
- Send top/bottom using MPI async calls
- Compute middle
- Finish MPI receives
- Copy top/bottom to device
- ThreadSync to ensure middle is done

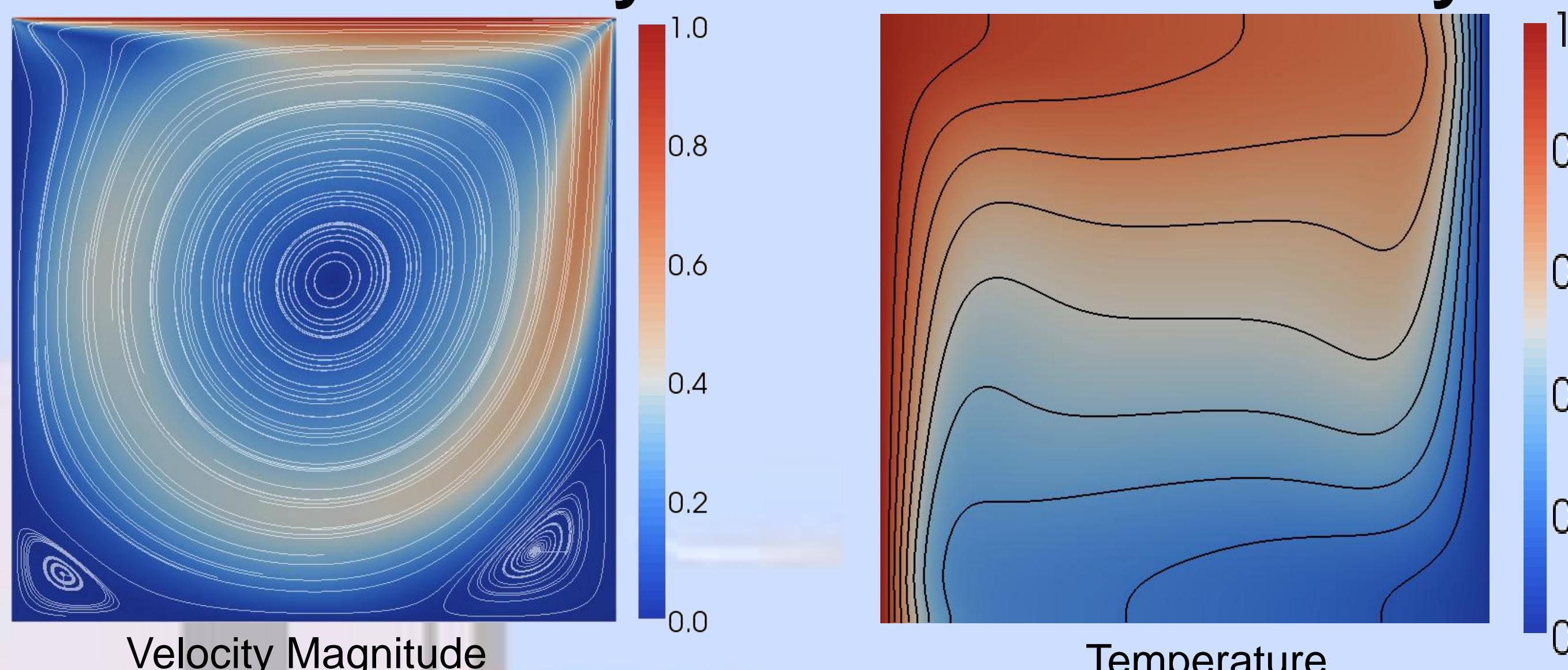
### CUDA Streams

- Does not overlap computation
- MPI and host/device copies are interleaved

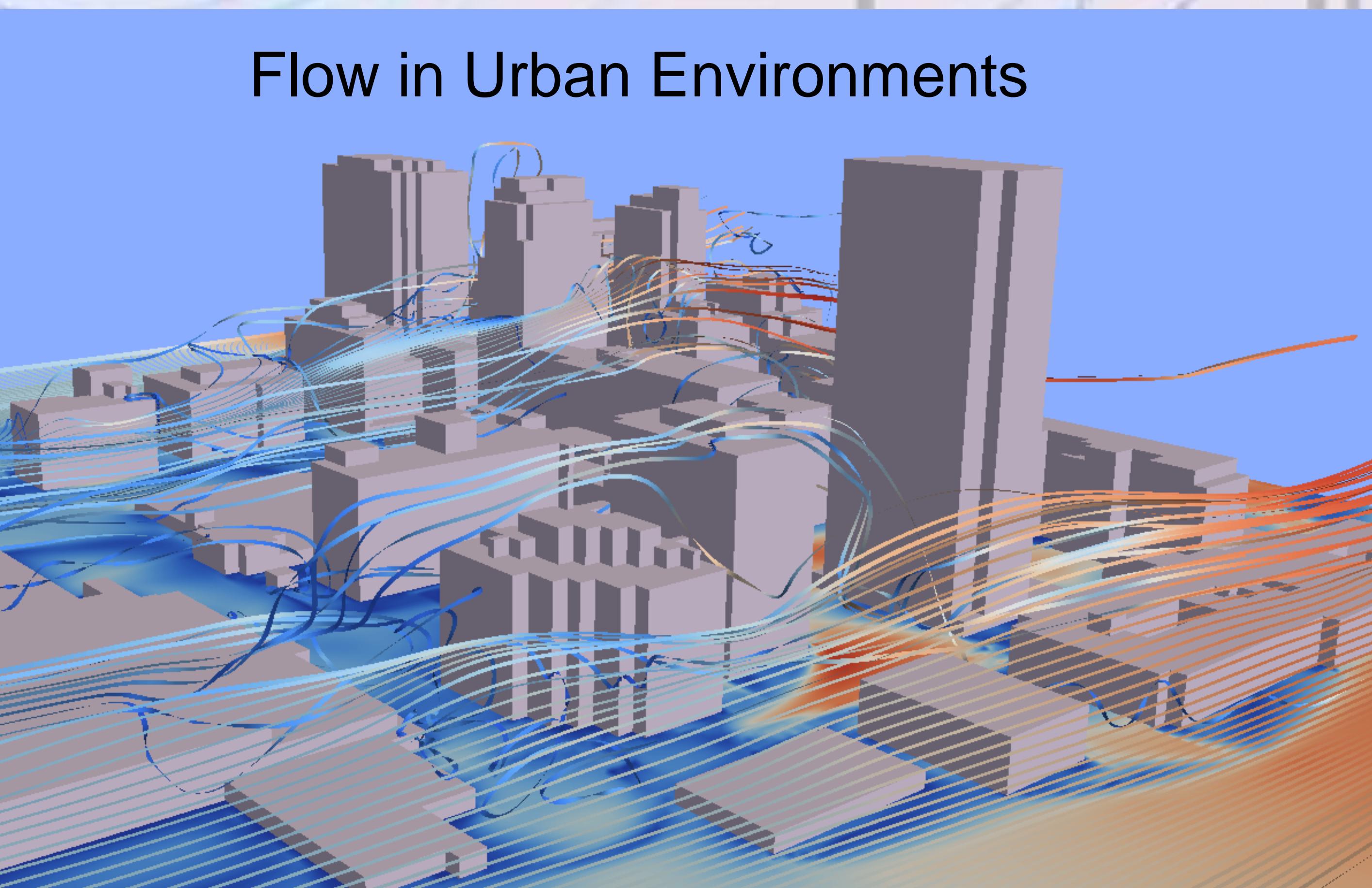
- Overlaps computation with copies and exchanges

## GIN3D Simulation Capabilities

### Lid Driven Cavity



### Heated Cavity

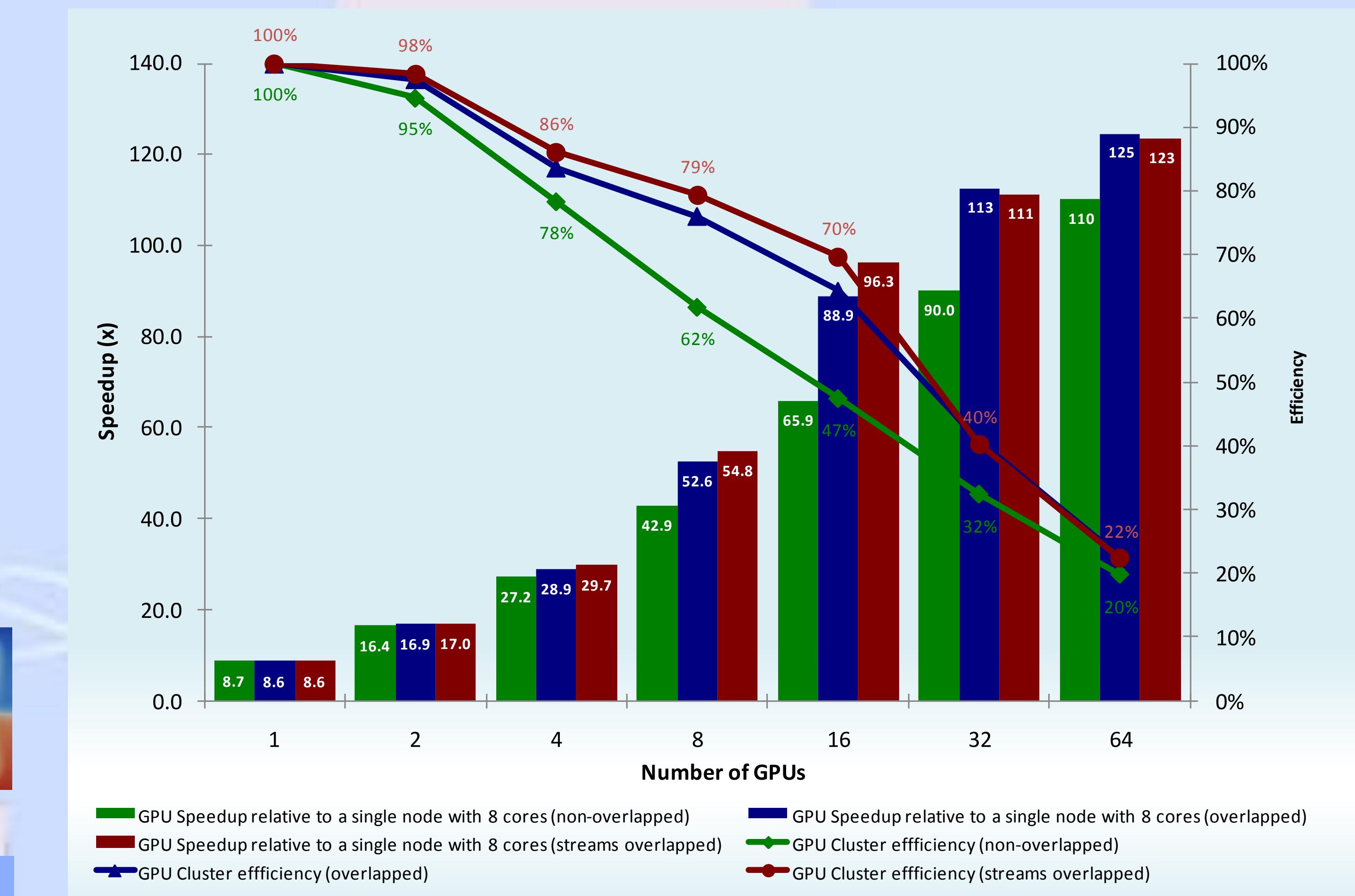


## Conclusions

- Overlapping MPI with device copy and computation is essential for scalability
- For fixed problem size, GPU interexchange quickly becomes a bottleneck
- Speedups relative to 8 CPU cores: 17x for 1 GPU node, 123x for 32 GPU nodes, and 453x for projected CPU performance

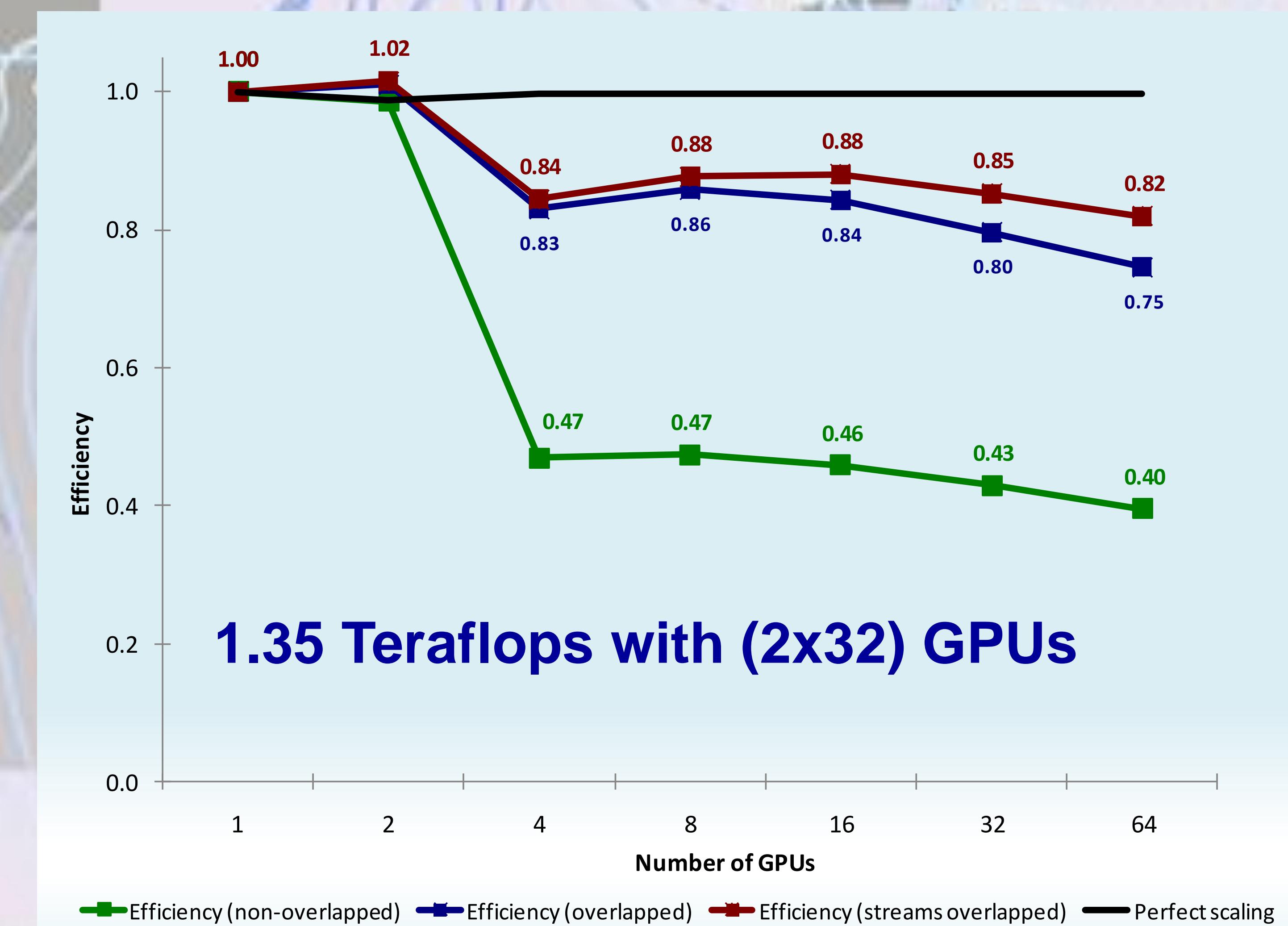
## Strong Scalability

Problem size fixed at 1024x64x1024



## Weak Scalability

Problem size per GPU fixed at ~3.8 GB



1.35 Teraflops with (2x32) GPUs