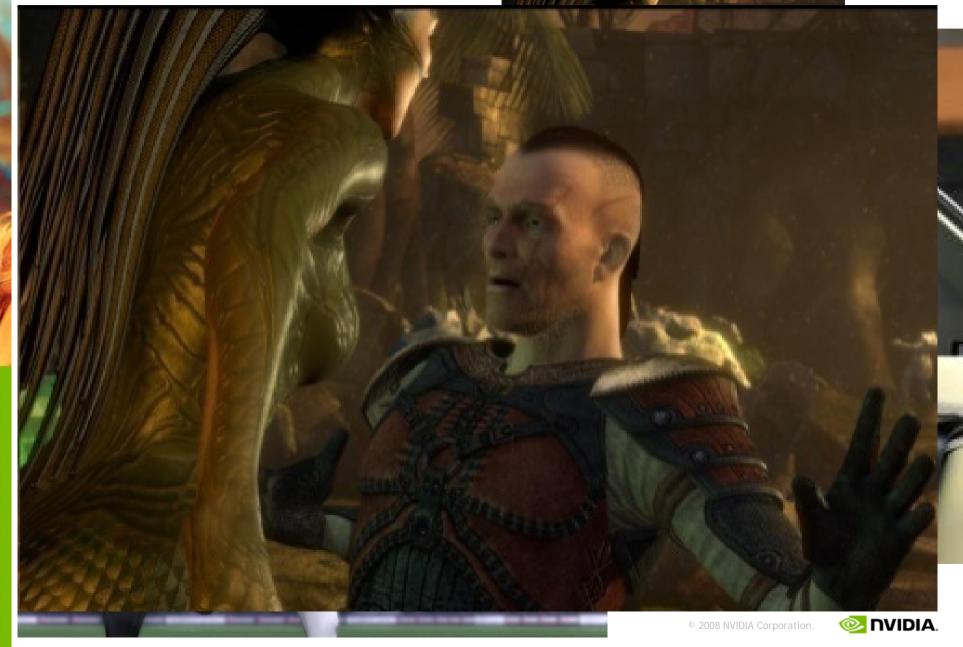


NVISION 08 THE WORLD OF VISUAL COMPUTING









PhysX Makes Graphics Come Alive





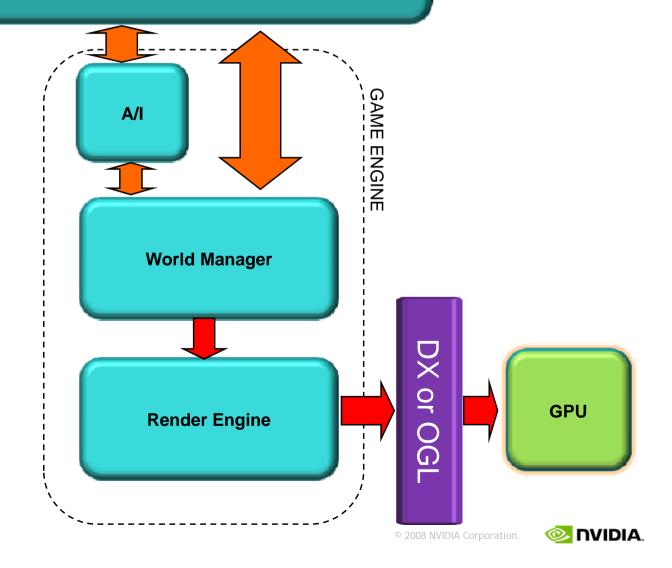


Come Alive PhysX Makes Games

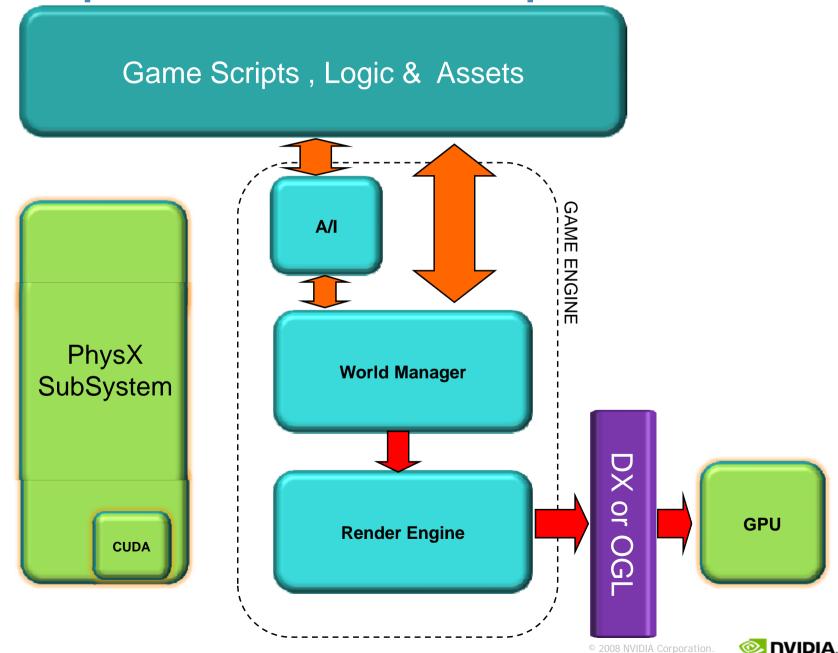


Simplified Game Pipeline

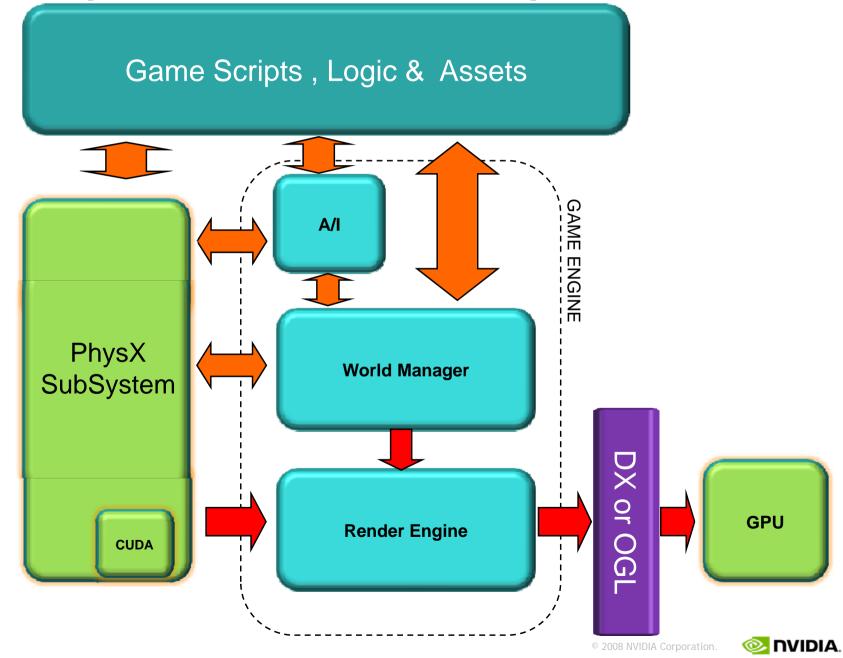
Game Scripts, Logic & Assets



Simplified Game Pipeline



Simplified Game Pipeline









Physical Phy





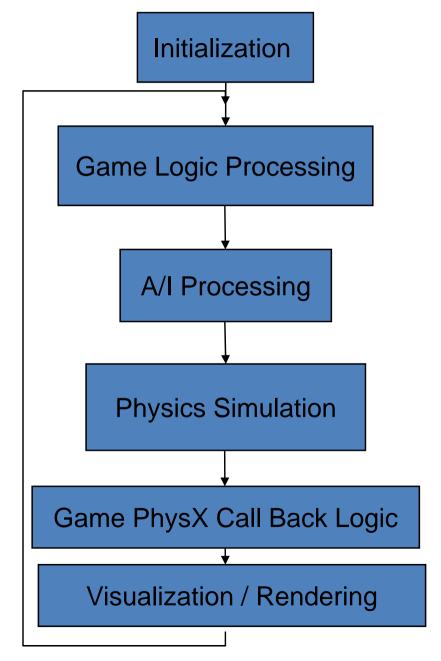


NVIDIA PhysX SDK Overview

- PhysX SDK is a complete Physics Solution
 - Comprehensive API
 - Library of auxiliary methods (Cross platform)
 - "Cooking" Library
 - Development Tools
 - Multi-Media Documentation
 - Multi-Tiered Support
 - Extensive Industry Eco-System

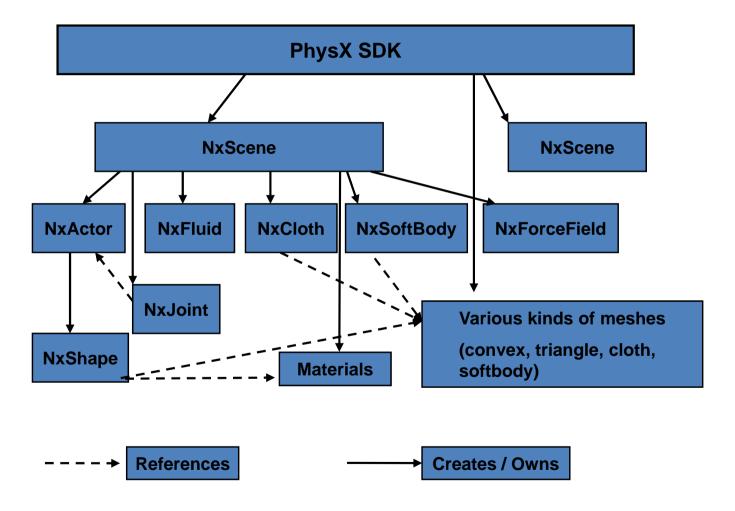


Simplified Game Flow With PhysX





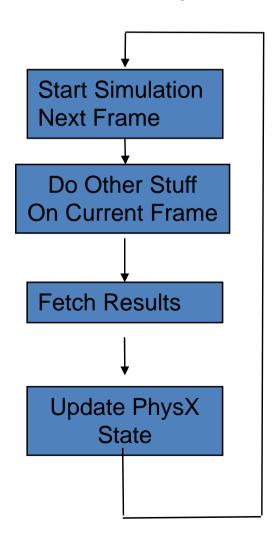
PhysX Object Model



PhysX Runtime

- Asynchronous Simulation Core
 - Rigid Body
 - Fluid
 - Cloth
 - Soft Body
 - Force Field
- Additional Functions
 - Scene Query
 - Character Controller
 - Vehicle Controller

Game Loop





Rigid Body

Actor

- Static fixed in world space
- Dynamic and have 'body'
- One or more Shapes
 - Geometry
 - Relative Transform
 - Material
- Dynamic Body
 - Velocity (linear & angular)
 - Mass properties
 - Sleep properties
 - Can form mechanisms



Rigid Body

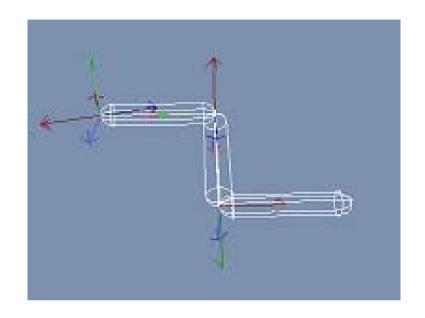
Joints

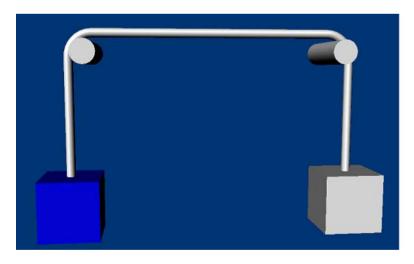
- a frame in each actor
- constraints on those frames

D6 and 8 additional types

Includes support for

- Motors
- Springs
- Limits
- Pulleys

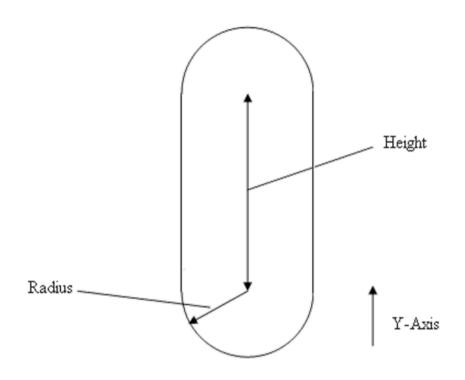






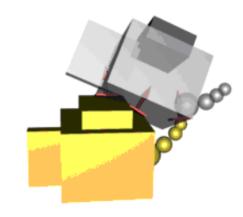
PhysX Shapes

- Single or Meshes
 - Capsule
 - Sphere
 - -Box
 - Convex Mesh
 - Triangle Mesh



Physics Shape





Graphics Representation

Bounding Box Representation

The Kinematics of any rigid body can be represented by a tensor and point.

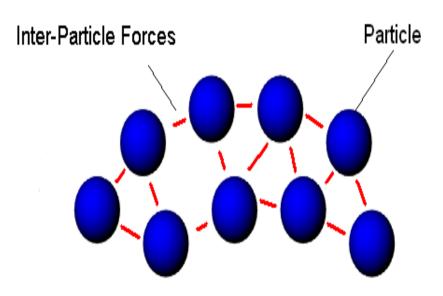
Physics representation does not need to be same of the graphical mesh.



THE WORLD OF VISUAL COMPUTING

Fluid

- Colliding particle system
 - Position, velocity, lifetime, density,



- Interaction Modes
 - SPH
 - Non-interacting
 - Mixed



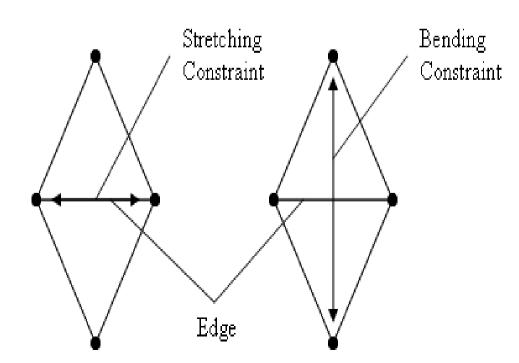
Fluid

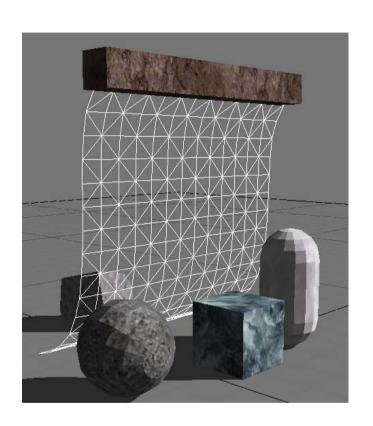
- ParticleManipulation
 - add, update, remove particles
- Packet-based culling
- Emitter (Source)
 - can attach to shapes
- Drain (Sink)
 - NX_SF_FLUID_DRAIN flag on shape
- Event Notification



Cloth

- Mesh of particles
- Stretching and bending constraints







Cloth Parameters

NxCloth class parameters

- Bending Stiffness
- Stretching Stiffness
- Density
- Thickness
- Damping
- Solver Iterations
- Attachment Response Coefficient
- Collision Response Coefficient
- Friction
- External Acceleration
- Wind Acceleration
- Valid bounds
- + Selection of Flags to enable various affects



Cloth

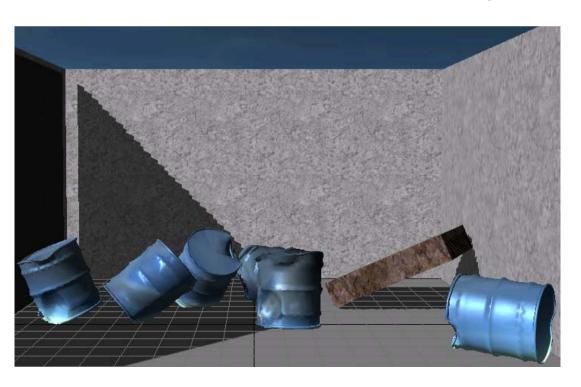
Attachment

- Attach vertex to fixed points or shapes
- Detach vertex
- Tearing
 - automatic or explicit
 - tearable attachments
- Pressure
 - Closed meshes only
- Collision
 - Self-collision
 - Collision with rigid bodies



Metal Cloth

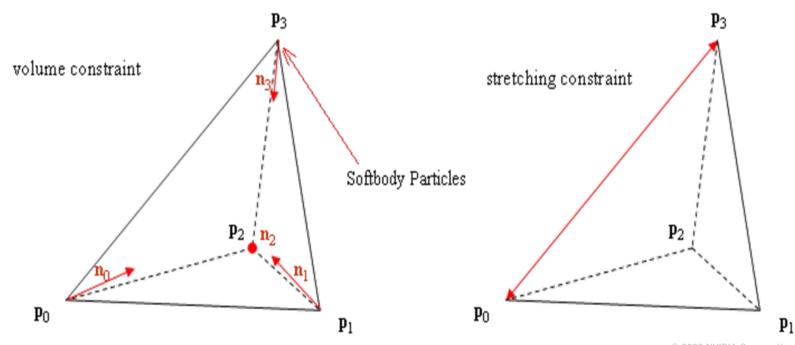
- Derivative of Cloth Feature
 - Plastic deformation of sheet metal
 - Cloth mesh around a rigid body core
 - On impact deform the mesh & adjust RB collision





Soft Bodies

- Mesh of particles
- Volume-preserving tetrahedral constraints
- Uses cloth Solver

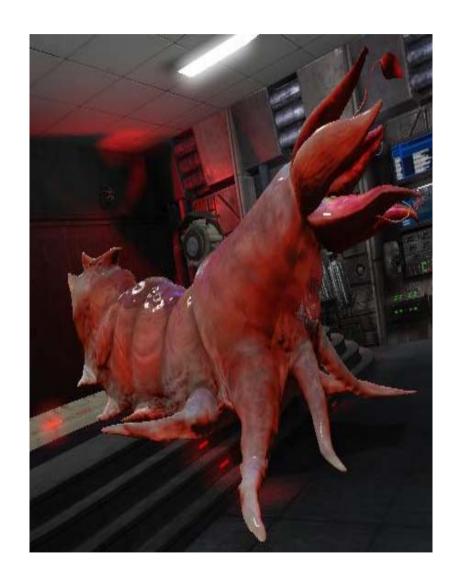




Soft Bodies

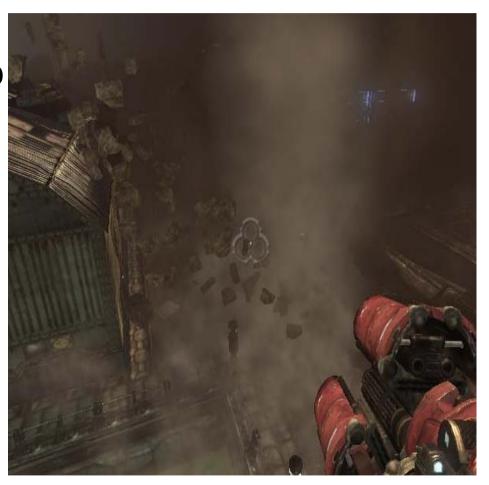
- Creation
 - RequiresTetrahedralization
 - Tetra-maker in PhysXViewer!

Attachments & Tearing



Volumetric Force Fields

- Enables procedural insertion of energy into the system
- Activity volume
 - 'Include' & 'Exclude' volumes
- Data-driven Fixedfunction Kernel
- Custom Kernel
 - Procedural shaders compiled at compile time and runtime



Tornado example FF provided in SDK



Other SDK Functionality

- Scene Query
 - Raycast
 - Swept Volume:Box/Capsule/Actor
 - Batching & Sweep Cache for performance
- Character Controller
 - A box- or capsule- shaped actor
 - Sweep tests for ease of walking
 - Ships with source
- And More ...



Cooking

- Offline Asset Preprocessing
 - AABB Trees for Triangle Meshes
 - Convex Hull from point set, plus acceleration cube map
 - Cloth from tri-mesh, soft body from tet-mesh
- All assets cook to binary stream
- Conditioning
 - Vertex welding
 - Optional inflation and edge beveling for thin/sharp objects



PhysX Development Infrastructure

- APEX
- AgPerfmon
- PhysX Visual Debugger (VRD)
- SoftImage PlugIns
- Max PlugIns
- Maya PlugIns
- PhysXViewer
- TetMaker
- Video Tutorials





APEX Mission: Solve 3 Big Game Physics Problems

1. Significant programmer involvement

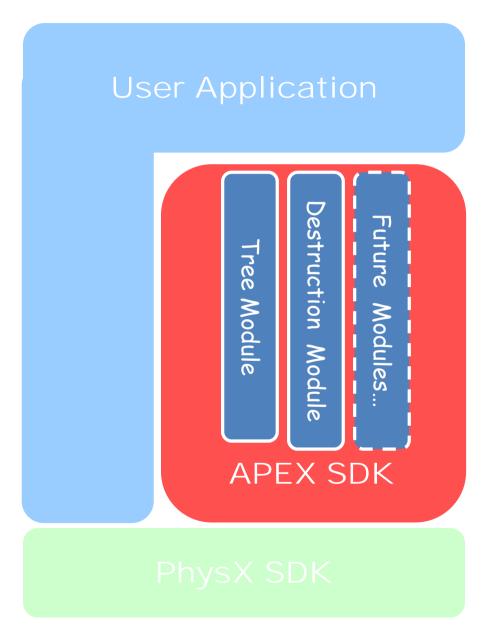
2. Content designed to "min spec"

3. Game engine limitations



Basic Design

- A collection of "modules"
- Shared interfaces
- Built on top of the PhysX SDK
- User Application:
 - Game (runtime)
 - Authoring tools
 - Level editor





Modules

- Implement intuitive, specific purpose, high-level physics technology
- Level of abstraction appropriate for content creators
 - Low SDK level of abstraction: rigid body, joint, cloth, fluid
 - High APEX level of abstraction (modules): vegetation, character, destructible mesh
- Manage multiple physics elements and simulation types



Authoring

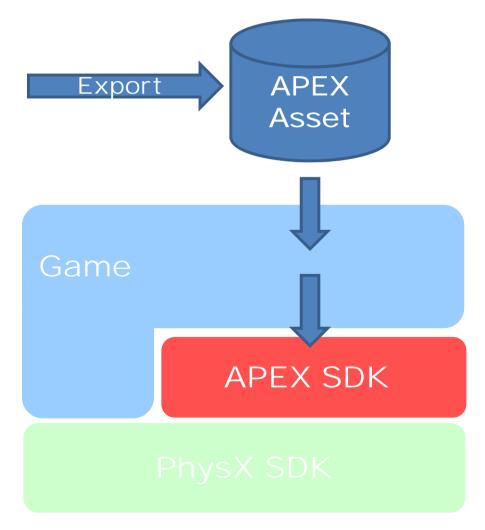
e.g. Maya

Apex Plugin

APEX SDK

PhysX SDK

- Modules are provided with authoring tools
- SDK has asset file serialization support built-in (load/store)



Problem 1

- Significant programmer involvement
- APEX Solution: Provide a "high-level" interface to the artists
 - Reduces the need for programmer time
 - Add automatic physics behavior to familiar objects
 - Leverage multiple SDK features



Scaling

- Scaling graphics was easy...
 - Scaling physics, not so much!
- All modules provide load-time and/or run-time scalability mechanisms
 - E.g. Number of APEX objects to have active, total number of debris to keep around
- APEX assets are authored once
 - ... to reduce work
 - But the developer still has control over scaling and LOD



Problem 2

- Content designed to "min spec"
- APEX Solution: scalable modules
 - Variable physics "quality" for each physical system
 - Static: hardware capability, player preference
 - Dynamic: visibility, distance from player, etc.

Interface to Rendering System

- APEX has a unified API for sending data directly to the rendering engine
 - Shared by all modules
 - Bypass game logic whenever possible
 - Efficient, but flexible
- Application implements a few interfaces
 - APEX objects ask the game to allocate buffers
 - APEX streams rendering data to the buffers
 - Application renders the buffers with appropriate materials, shaders, etc...



Problem 3

- Game engine limitations
- Solution: Create a rendering "fast path"
 - Bypass the inefficient, fully generic path
 - PhysX objects in an APEX asset are scriptable / networkable / etc. as a group, not individually

Destruction Module

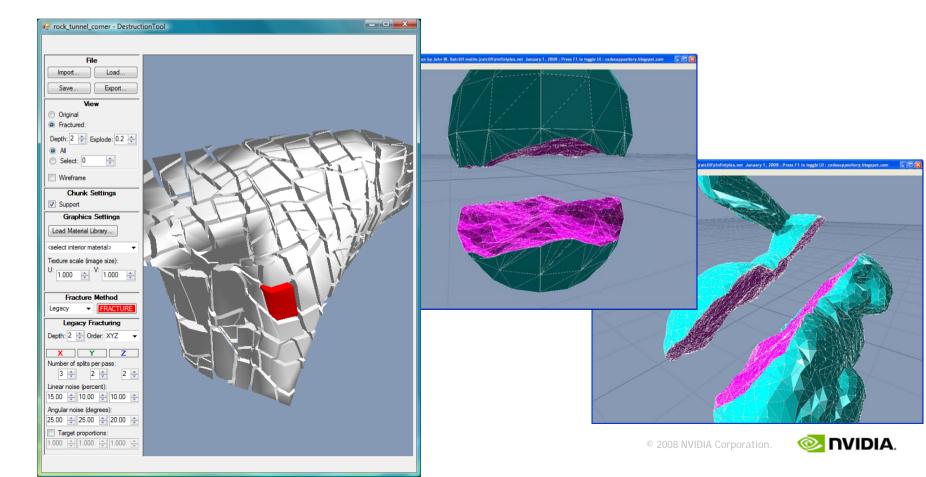
- Arbitrary meshes are pre-fractured at authoring time
- In real time as they take damage, pieces get blasted away
- Meshes can be initially static or dynamic
- "Support" system for static meshes
- Automatic small debris effect using particles





Destruction Authoring

- Standalone tool, easily integrated into 3dsmax, Maya, or XSI
 - Hierarchical splitting with random fracture surface generation



Destruction Scalability

- At authoring time:
 - # of pieces the original asset is split into
- At runtime:
 - Whether to fracture down all the way to the finest level of pre-fracture, or only to a coarser level
 - Option to scale amount of particle meshes
 - Size adjustable global debris FIFO
- The game can change runtime APEX parameters based on LOD.

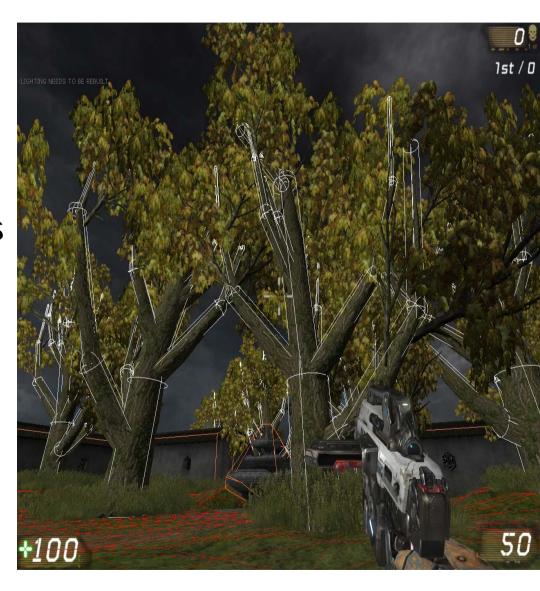


Tree Module

- Lets us create trees with physical behaviors
- Works with SpeedTree trees
- Full physical interactions
- Tree destruction
- Leaf dropping effect

Tree Physics

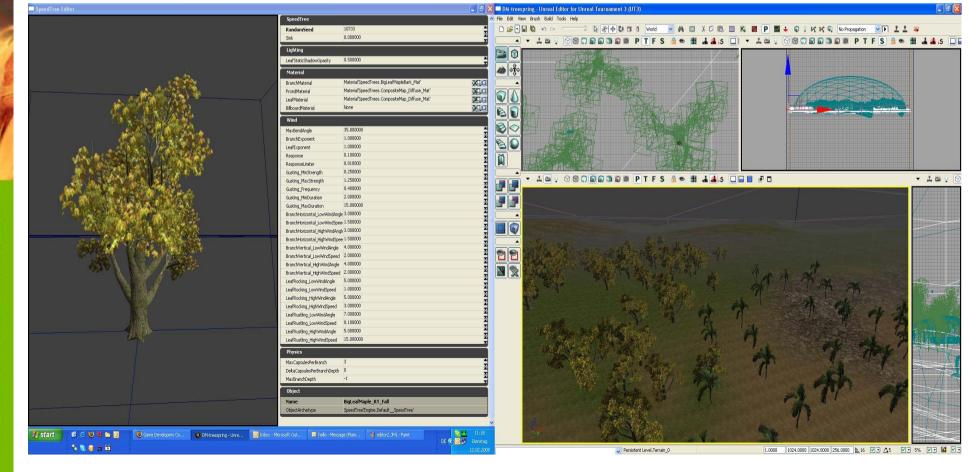
- Trees skeletons are automatically generated
- Skeletons are only simulated when trees are being interacted with (LOD)
- Emitters are automatically created to spawn leaves





Tree Authoring

- Authoring process same as for normal trees, except for a few simple physics parameters
 - Capable of directly loading SpeedTree format files



Tree Scalability

At load / authoring time:

A particular tree asset can have variable detail RB skeleton generated

At runtime:

- A large forest can have more or less of its trees become physically active at any one time, in response to interactions
 - Tree actor FIFO for fast activation
- Leaf emitters can emit more or less leaves

More modules...

- Actively seeking great ideas
 - and partners to work with...

What would you like to see?



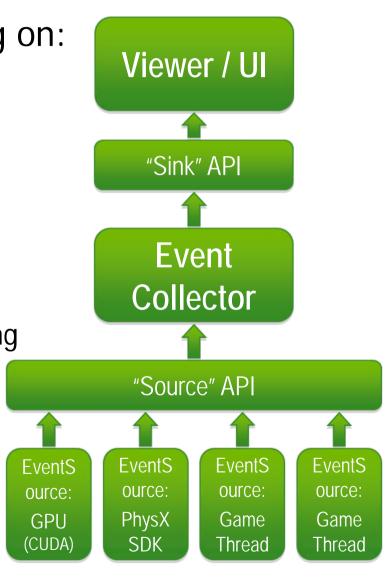
Problem Statement

- Identifying system-wide bottlenecks is very challenging
 - Many asynchronous processes running in parallel on different processing cores
 - Can't just analyze who's using the most cycles: dependencies matter
 - Visualizing "what happens when" is critical

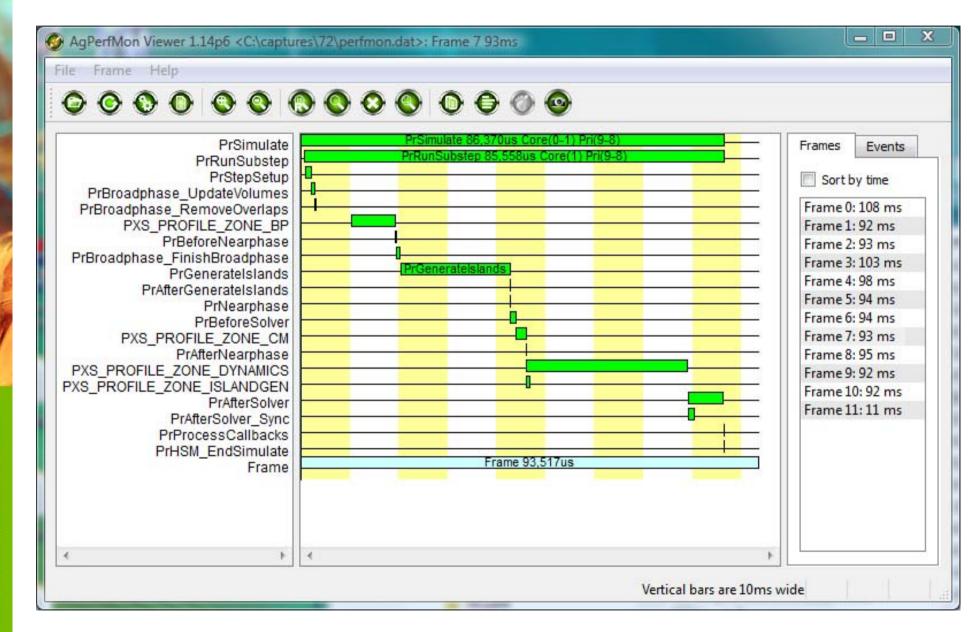


AgPerfMon Overview

- Supports simultaneous profiling on:
 - CPU Threads: PhysX / APEX SDKs, game / application threads
 - GPU: CUDA Kernels, Warps
- Event-logging architecture
 - Synchronized time stamps
 - Configurable source-based filtering
 - Configurable event triggers
 - Periodic event generation
 - Source & sink API's
 - VERY lightweight



Event Viewer



Source API - Initialization

YourCode.cpp:

```
#include "AgPerfMonEventSrcAPI.h"

// Initialization code
AgPerfUtils *gPerfUtils = new AgPerfUtils;
```

```
// Shutdown code
delete gPerfUtils;
```

Source API - Event Generation

AgPerfMonEventDefs.h:

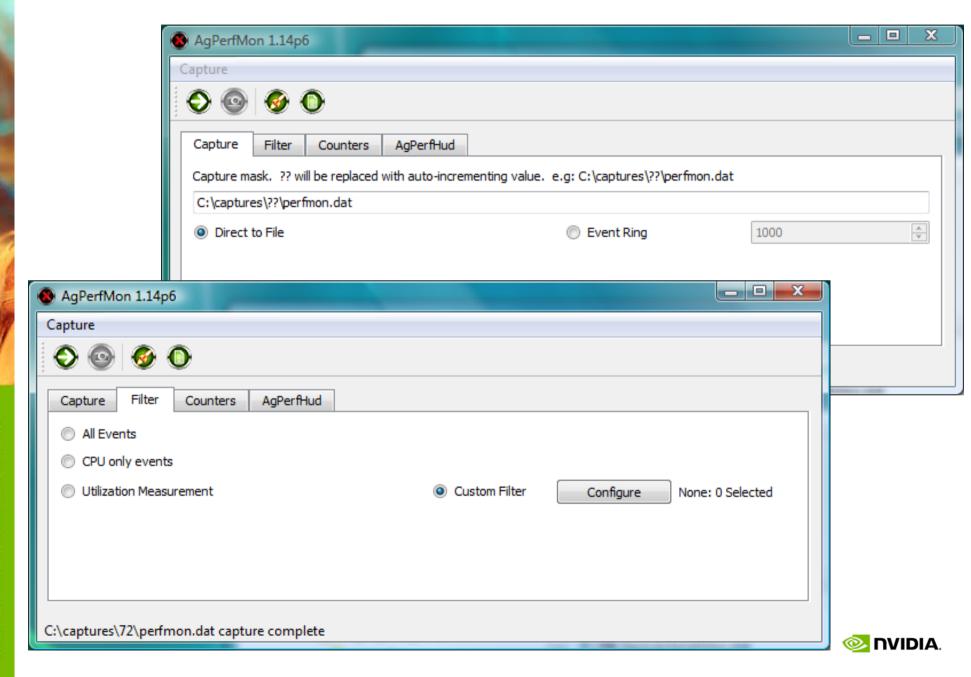
DEFINE_EVENT(Foo)

YourCode.cpp:

```
AgPerfScope s(Foo);
// do something
}
```



AgPerfMon GUI



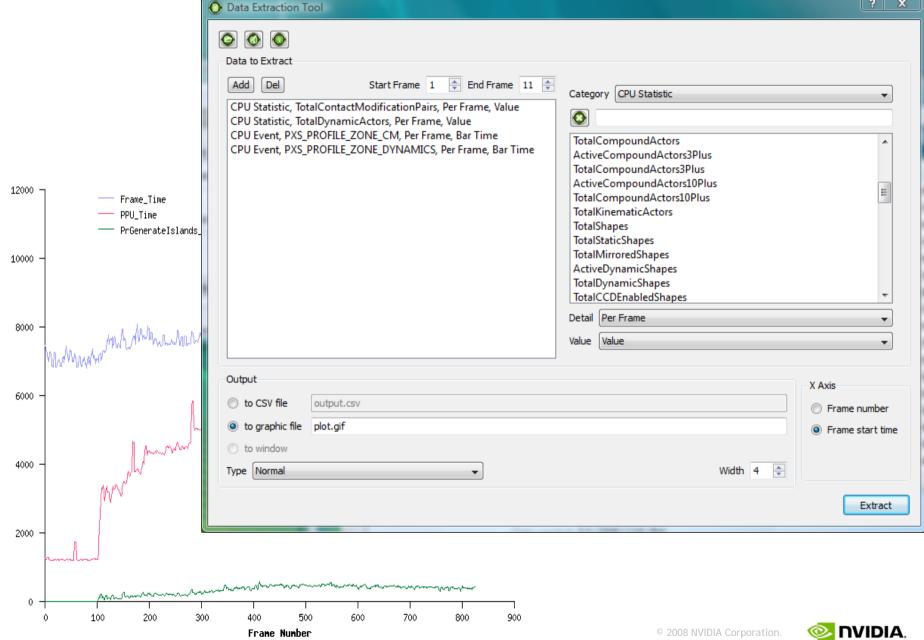
AgPerfMon Viewer

Frame events

- Define frame boundaries
 - Frame Start Event marks the start of frame...
 - ... only if a Frame End Event has been seen since last start of frame
- No frame events
 - View entire file as a single frame
 - Only works for small files
- Index cache
 - Viewer builds an index cache to accelerate finding frames in large data files (*.fdx)



Data Extraction Tool



AgPerfHud

 Simple utility to overlay AgPerfMon performance data on any D3D application window

AgPerfMon 1.14p6		_ D X
Capture		
♦ ♦ ♦		
Capture Filter Counters AgPerfHud		
Application Path		
		▼ Browse
Arguments	Profile Event	
	▼	▼ Browse
Start Application Start Collector		
C:\captures\72\perfmon.dat capture complete		







Visual Remote Debugger (VRD)

- Connects to a running PhysX SDK through a network socket
- Provides access to all simulation state data
 - Live visualization
 - Record / playback / save to file
- Full visualization of physics scene
 - Shapes / bounding boxes / particles
 - Contacts / joints
 - Velocities
- Data editing
 - Click on an object to view / modify state in "Scene Browser" window



Unreal Tournament 3





Platform Coverage

	Phys X by NVIDIA	Competitor's Solution	
PC Support - CPU only	YES Multi-Threaded Support for Multi-Core x86 Products	YES	
PC Acceleration	YES! GPUs (CUDA): Mobile + Desktop	NO	
Xbox 360	YES	YES	
Playstation3	YES	YES	
Wii	YES*	YES	

PhysX License Fees

Per Game License Fee	PC³	PS3 ¹	Xbox 360	XBLA	Wii ²	Wii- Ware
Binary	Free	Free	Free	Free	Free	Free
Source	\$50K	\$50K	\$50K	\$50K	\$50K	\$50K

¹ The PS3 PhysX SDK has been maintained and supported by Sony. If you are a PS3 registered developer, you can find the PhysX SDK on Sony's online download site. NVIDIA will soon take direct ownership of licensing.

- ² Wii SDK in Beta
- ³ Linux Driver Support Available

PhysX License Fees

Binary SDK

- SDK Unified PhysX API for both PC and Console Platforms
- PC Binary SDK Free for both Commercial <u>AND</u> Non-Commercial use
 - No License Fee Required
 - Over 30,000 Downloads
- Console SDK's Free for Registered Developers for both Commercial AND Non-Commercial use
 - EULA covers terms

Source SDK

- Individual Game License for each Platform
 - Multi-title flexibility on terms
- Source Code SDK includes HL source code to facilitate debugging process



Developer Support

- Multi-language documentation on the way:
 - Japanese, Chinese, and Korean
- Two Levels of Support:
 - Free forum support always available via NVIDIA's developer website
 - developer.NVIDIA.com/forums
 - Ticket-based support and staffed in local timezones worldwide
 - Paid Support Model \$8k annual/game/platform

